# Large area SEM mapping using the Rapid Stage and its benefits for EDS, WDS and micro-XRF analysis





#### Presenters





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01.05.2020

#### Overview



- Terminology
- Introduction to Rapid Stage
- Types of Large Area Mapping on a SEM and Potential Issues
- Differences between SEM-EDS / SEM-WDS / SEM-XRF -Rapid Stage Technical Description
- Example Applications and Benefits
- Summary and Conclusion

01.05.2020

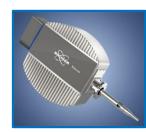
## Introduction Terminology



**SEM-EDS:** Analysis based on the sample interaction with an electron beam source from the SEM and the resultant X-rays that are detected using an EDS (simultaneous element detection)



**SEM-WDS:** Analysis based on the sample interaction with an electron beam source from the SEM and the resultant X-rays that are detected using a WDS (sequential element detection)



**SEM-XRF-EDS: MicroXRF on SEM (XTrace):** Analysis based on the sample interaction with an X-ray beam source from the Micro XRF attached to the SEM and the resultant X-rays that are detected using an EDS (simultaneous element detection)



Rapid Stage: New high speed stage with precision movement



SEM Stage: Standard stage that comes with the SEM

## Analytical Parameters and Conditions SEM-EDS vs SEM-WDS vs SEM-XRF



Parameter	EDS: E-beam	WDS: E-beam	EDS: Micro-XRF
	(SEM-EDS)	(SEM-WDS)	(SEM-XRF-EDS)
Analyzed Volume	Ø: few µm Information depth: µm; (depending primarily on electron energy)	Ø: few µm Information depth: µm; (depending primarily on electron energy)	Ø: 15-30 µm Information depth: µm to mm; (depending on analysed element and matrix)
Detectable Elements	Atomic number Z ≥ 4 (beryllium)	Atomic number Z ≥ 4 (beryllium)	Atomic number Z ≥ 6 (carbon)
Energy range	K- L-M - Lines ( up to 20 keV)	70 eV - 3.6 keV (L- M- Lines)	K- L -M - Lines ( up to 40 keV)
Concentration Range	Down to 1000 ppm	Down to 100 ppm	Down to 10 ppm
Quantification	Standard less and Standard based	Standard based	Standard less and standard based
Data collection	Simultaneously	Sequentially	Simultaneously
Sample Preparation	Sample needs to be electrically conductive (commonly carbon-coated), polishing required	Sample needs to be electrically conductive (commonly carbon-coated), polishing required	Electrical Conductivity not required, samples doesn 't need to be polished
Sample Stress	Heating due to absorbed electrons	Heating due to absorbed electrons	Minimal
Typical SEM beam current	Variable	Variable > 10 nA	N/A

#### Introduction

#### **Historic and Current Webinars**



#### www.bruker.com/events/webinars.html

Filter: EDS, WDS, EBSD, Micro-XRF on SEM

High Speed Mapping Using Micro-XRF on SEM



Advanced elemental analysis of geological samples using QUANTAX WDS for SEM



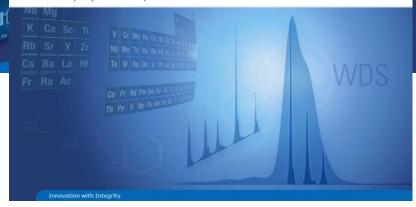
Bruker Nano Analytics, Berlin, Germany Webinar, April 25, 2019

Bruker Nano Analytics, Berlin, Germany Webinar, November 6<sup>th</sup>, 2019

Microanalysis with high spectral resolution: the power of QUANTAX WDS for SEM



Bruker Nano Analytics, Berlin, Germany Webinar, September 14, 2017



Advancements in Microanalysis with micro-XRF on SEM





Bruker Nano Analytics, Berlin, Germany Webinar, April 18<sup>th</sup> 2018



### Application of Rapid Stage Motivation



#### Why using Rapid Stage for SEM-EDS and SEM-WDS?

- Enhancing speed for mapping applications
- Enhancing EDS / WDS usability
- Enabling WDS mapping with vertical beam at the speed of a beammap
- Avoiding Bragg's law violation
- Avoiding lateral intensity loss
- Enabling large scale mapping

#### Why using Rapid Stage for SEM-XRF?

 Enhancing speed for mapping applications as only stage mapping is possible as the X-ray beam is fixed in space and can not be rastered

## Rapid Stage for SEM's Introduction

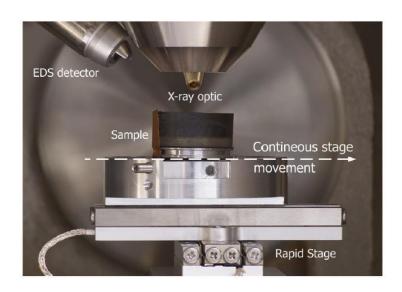




## Introduction Rapid Stage



- The Rapid Stage has been developed to enable high-speed mapping over large areas via Stage movement
- It is mounted on top of an existing SEM stage, including stage adaption and sample holder.
- The Rapid Stage is controlled independently from the SEM stage and can operate up to a maximum travel speed of 4 mm/s.





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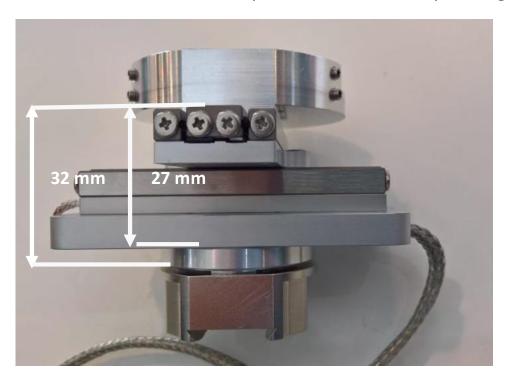
### Rapid Stage Dimensions



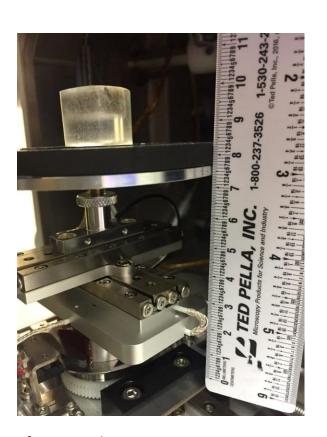
Stage itself (including x- and y linear positioners and basis plate): 27 mm

Including footplate: 32 mm

Without dovetail and sample holder → SEM depending



for Jeol IT 500 setup: 60 mm

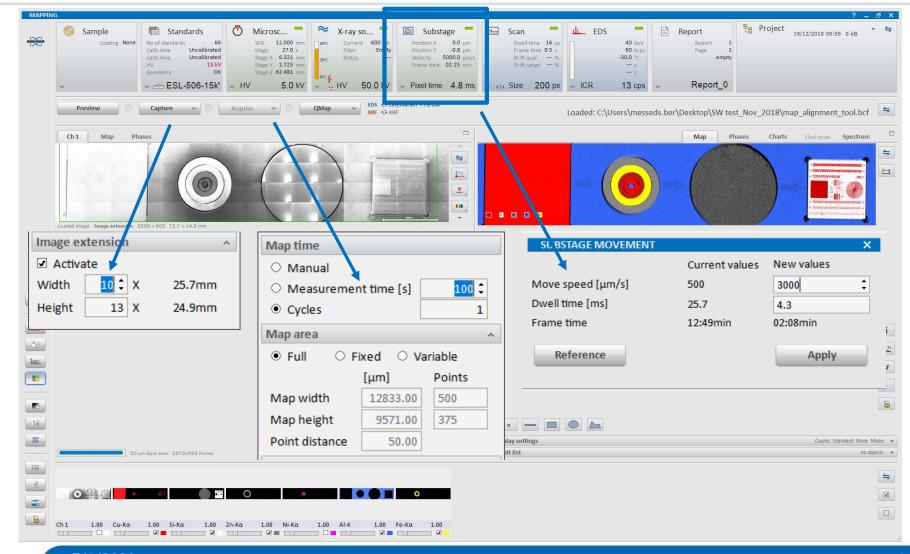


for Hitachi S3700N setup: **73 mm** 

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#### Rapid Stage Integration in ESPRIT





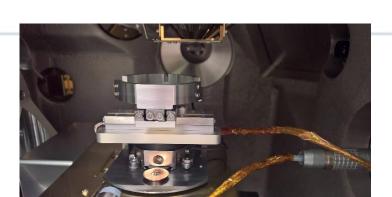
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# Introduction Video Rapid Stage



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### Rapid Stage Installations: Adaptable to various SEMs

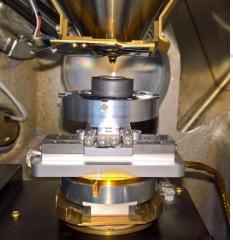


Jeol IT-500



Hitachi S 3700N





Jeol JSM 6490



Hitachi SU 3900

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### Rapid Stage Specification

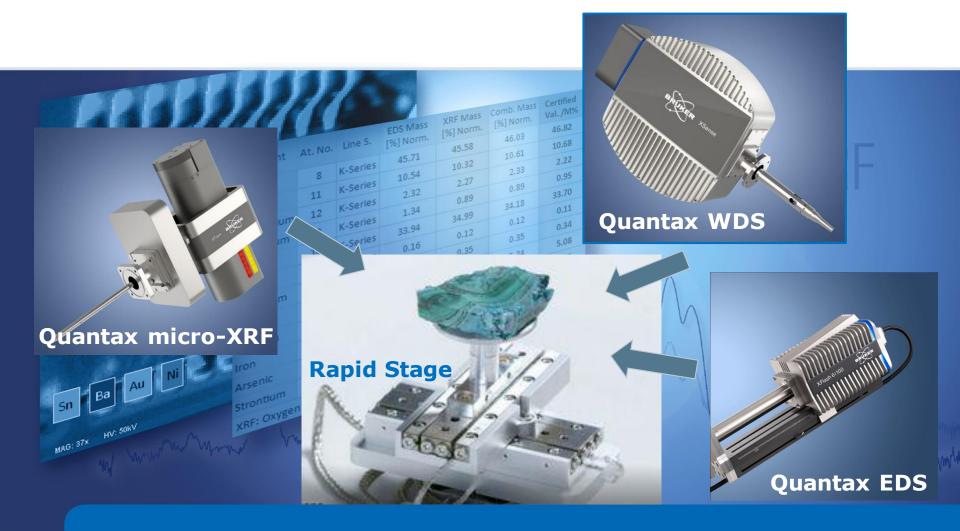


Parameter	Description	
Height	27 mm (without sample holder and SEM stage adaption)	
Weight	300 g	
Sample load	3 kg	
Stage travel speed	4 mm /sec	
Travel distance	50 mm	
Vacuum resistance	10 <sup>-6</sup> mbar (higher vacuum resistance on request)	
Resolution	< 1 nm	

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### Examples





### Rapid Stage Examples - Settings



Large Area Maps Overview: Mapping Types

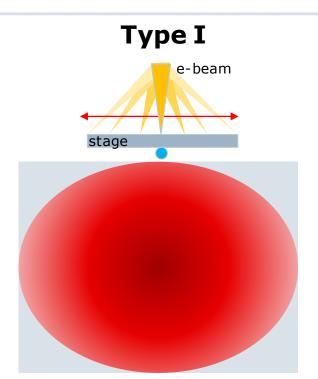
- Source: Electron Beam (e-beam) and X-ray beam
- Detector: EDS and WDS
- Stage: SEM-Stage and Rapid Stage

- ▶ Note: Combination (Simultaneous) data-sets
  - Rapid Stage with e-beam + X-ray beam + EDS, or
  - Rapid Stage with e-beam + EDS and WDS

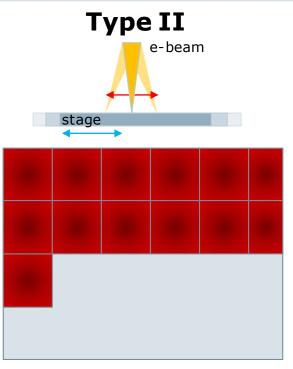
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## Large Area Mapping 3 Different Mapping Modes

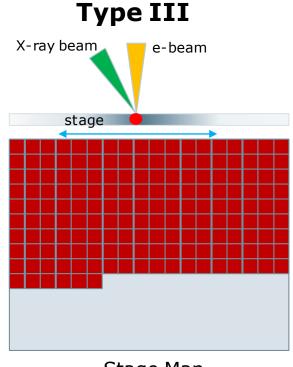




Scan Map Without Limits (Raster over Full Area) e.g. Low Mag. 30x



Scan Map With Limits
(Raster over Restricted Area
with Stage Movement)



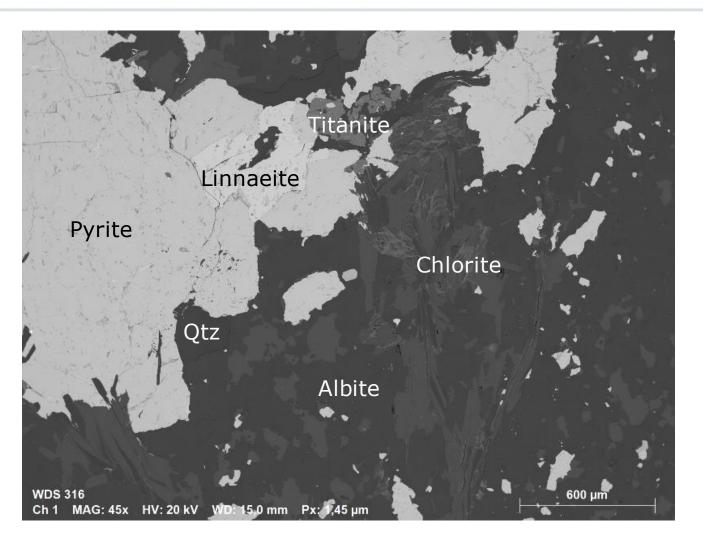
Stage Map
Independent of Magnification

Increasing accuracy - WDS

Increasing speed – SEM Stage

## Sample 1 Sulphide bearing rock





Low magnification 45x

Image dimensions:

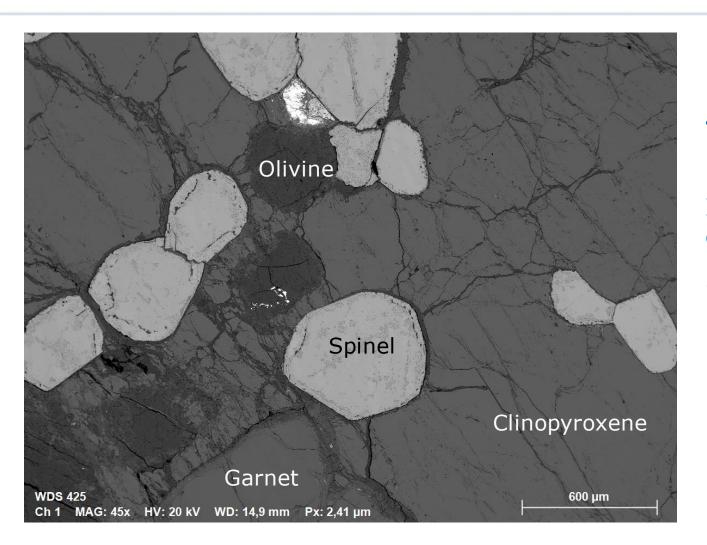
2.9 x 2.2 mm

**Resolution:** 

 $2000 \times 1500 px$  (1.45 µm / px)

# Sample 2 Garnet-Spinel Peridotite





Low magnification 45x

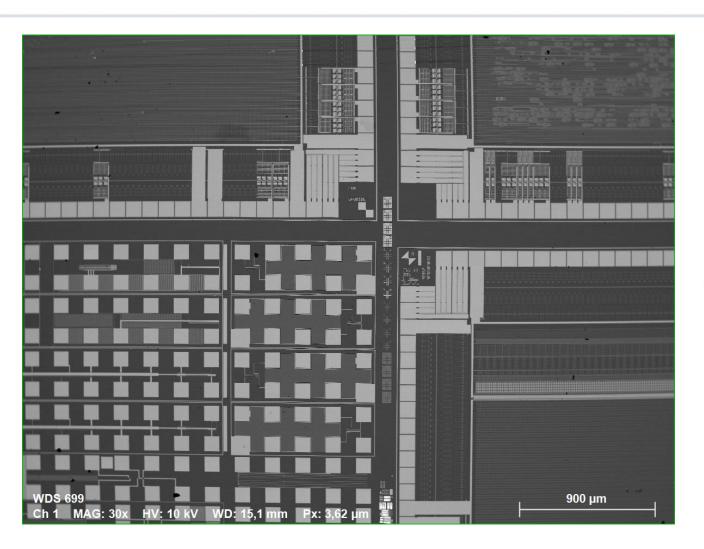
Image dimensions:

2.9 x 2.2 mm

Resolution: 1200 x 900 px (2.4 µm / px)

### Sample 3 Electronics Microchip





Low magnification 30x

Image dimensions:

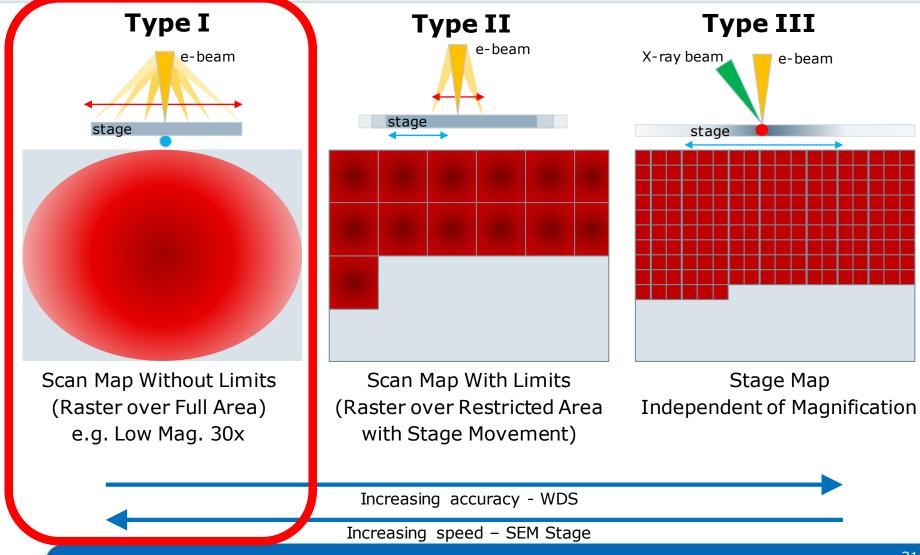
4.3 x 3.2 mm

**Resolution:** 

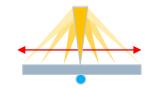
1200 x 900 px (3.6 μm / px)

# Large Area Mapping Type I

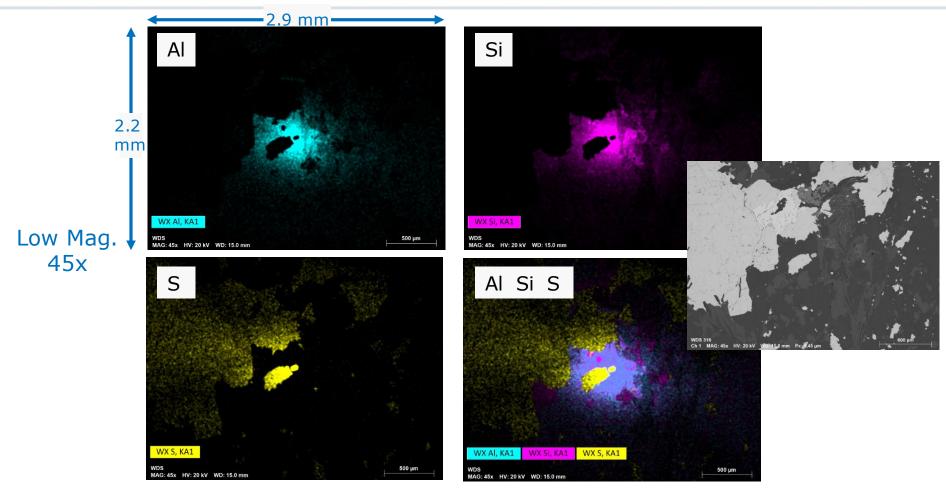




### Scan Map Without Range Limits Sample 1 at low magnification Single Field

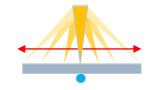




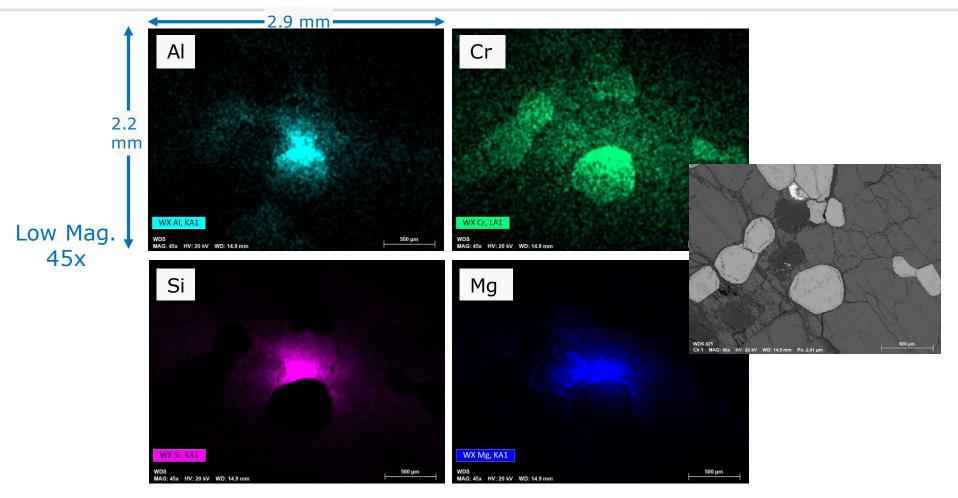


Type I Mapping: Low Magnification – Single Field Problems for WDS Mapping due to violation of Bragg's Law

### Scan Map Without Range Limits Sample 2 at low magnification Single Field

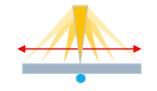




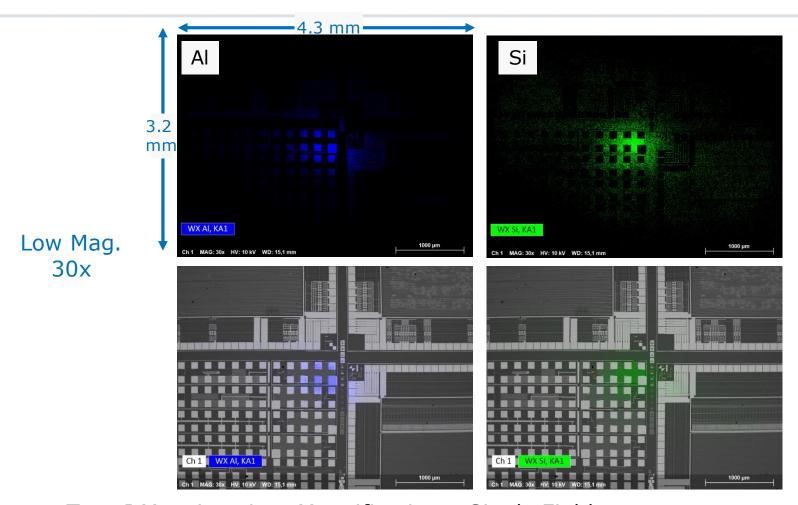


Type I Mapping: Low Magnification – Single Field Problems for WDS Mapping due to violation of Bragg's Law

# Scan Map Without Range Limits Sample 3 at low magnification Single Field

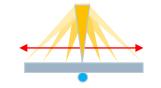




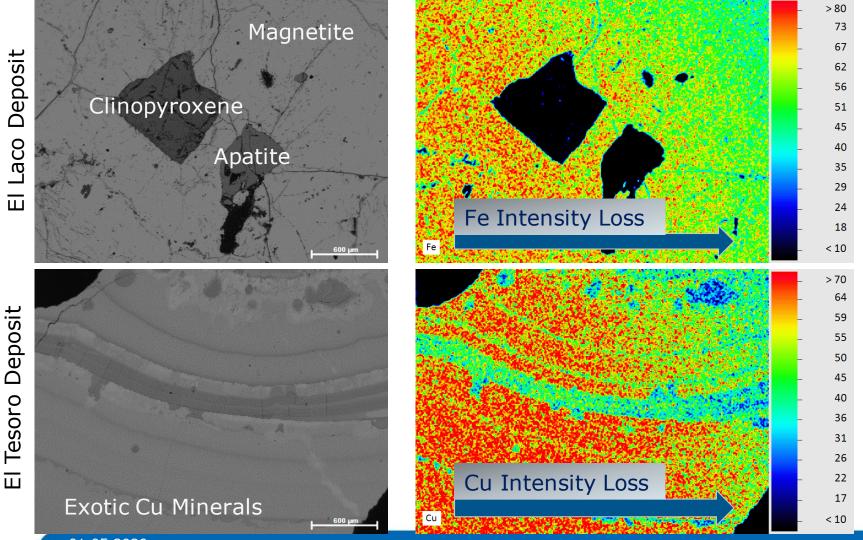


Type I Mapping: Low Magnification – Single Field Problems for WDS Mapping due to violation of Bragg's Law

# Scan Map Without Range Limits Sample 3 at low magnification Single Field

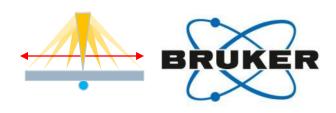


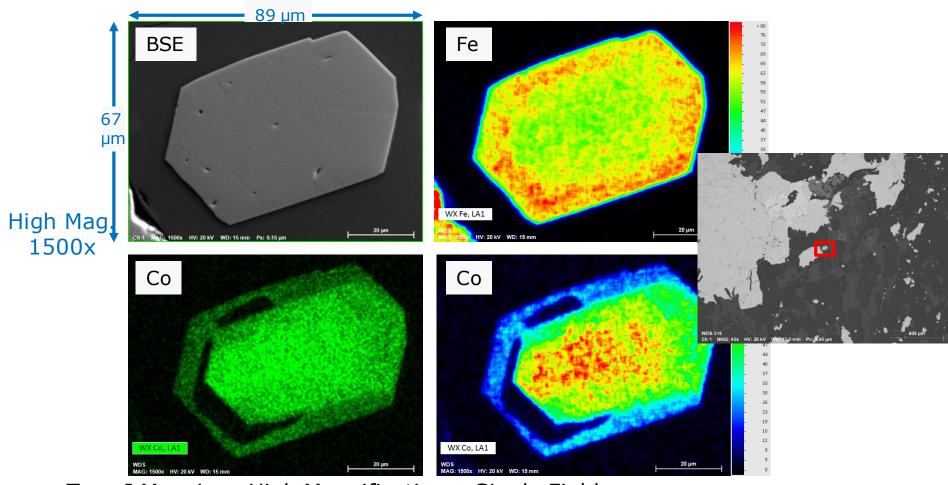




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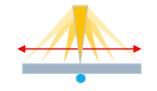
### Scan Map Without Range Limits Sample 1 at high magnification Single Field



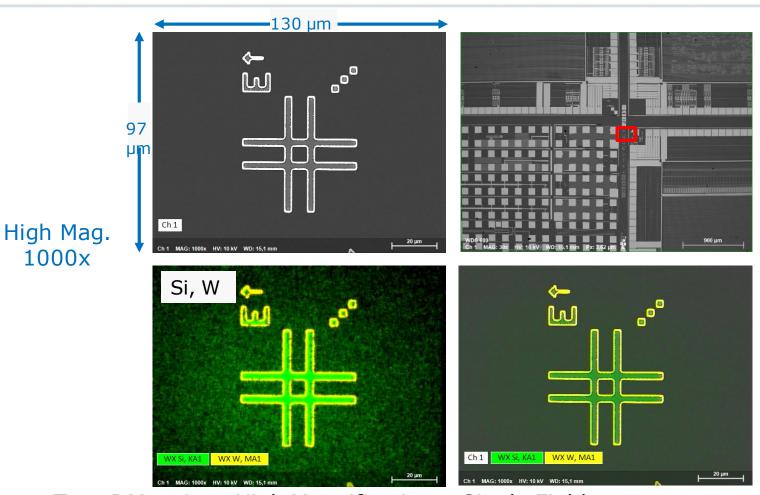


Type I Mapping: High Magnification – Single Field Suitable method for Small Areas where Bragg Angle Effect is negligible

# Scan Map Without Range Limits Sample 3 at high magnification Single Field





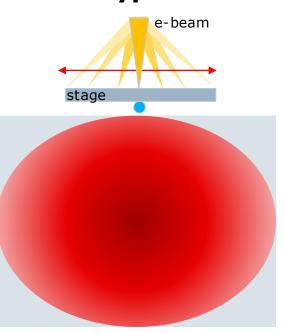


Type I Mapping: High Magnification – Single Field Suitable method for Small Areas where Bragg Angle Effect is negligible

## Large Area Mapping Type II

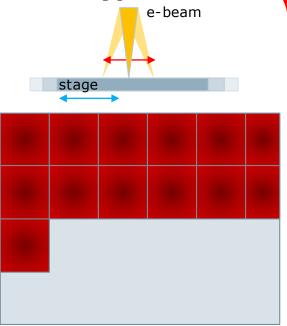






Scan Map Without Limits (Raster over Full Area) e.g. Low Mag. 30x

#### Type II

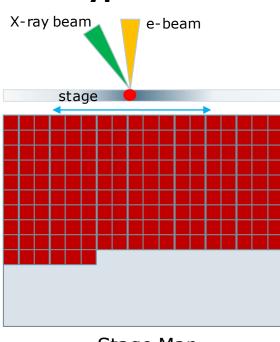


Scan Map With Limits
(Raster over Restricted Area
with Stage Movement)

Increasing accuracy - WDS

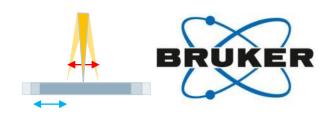
Increasing speed – SEM Stage

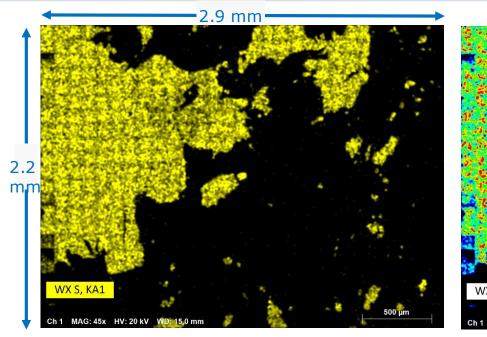
#### Type III

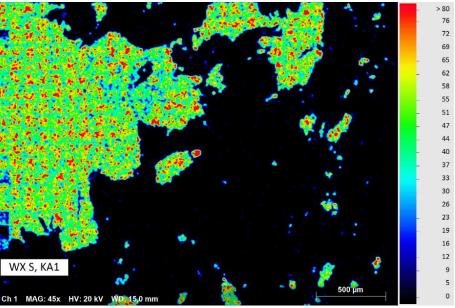


Stage Map
Independent of Magnification

# Scan Mapping with Range Limits Sample 1 at low magnification Segmented Map: 29 x 22 Tiles







- √ Faster than stage map
- ✓ Intensity fading reduced

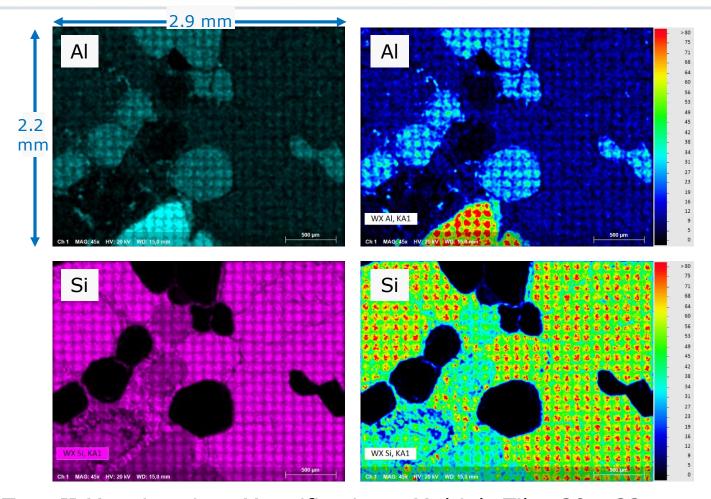
- Slower than scan map without limits
- Tiling may be visible

Type II Mapping: Low Magnification – Multiple Tiles 29 x 22

Bragg Angle Effect is lowered but may still be visible in mosaics

# Scan Mapping with Range Limits Sample 2 with Tiling at low magnification Extended Map: 29 x 22 Tiles



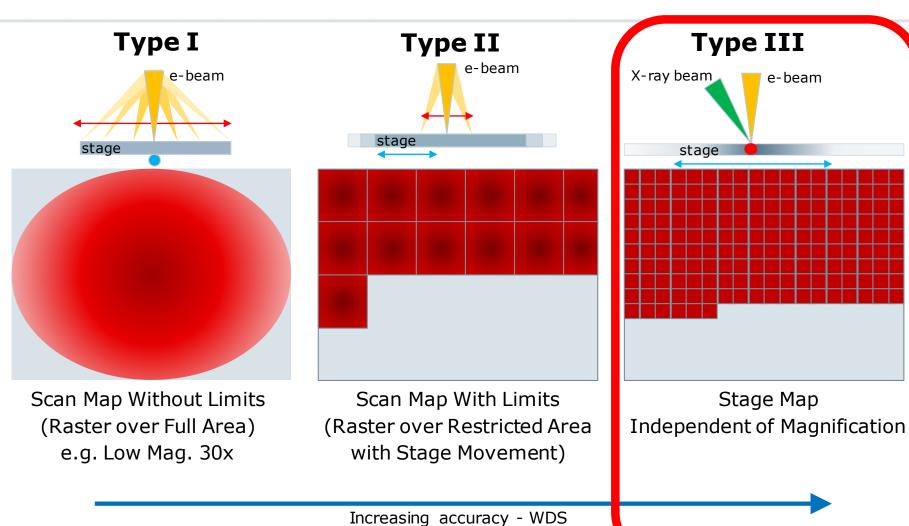


Type II Mapping: Low Magnification – Multiple Tiles 29 x 22 Bragg Angle Effect is lowered but may still be visible in mosaics

### Large Area Mapping

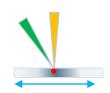
### Type IIIa: SEM Stage



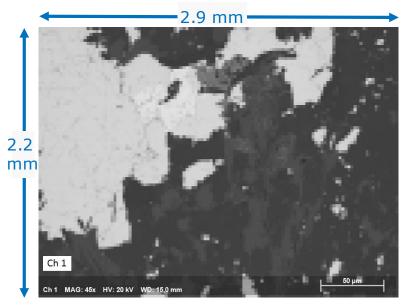


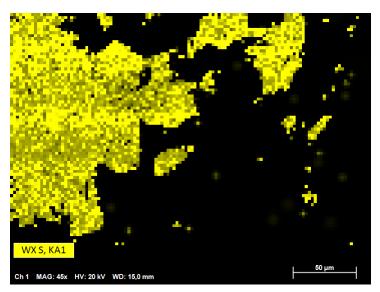
Increasing speed – SEM Stage

# Stage Mapping using SEM Stage Sample 1 at low magnification SEM-EDS/WDS









 $120 \times 90 = 10,800 \text{ px} \rightarrow 10 \text{ h}$ 

 $1200 \times 900 = 1,080,000 \text{ px} \rightarrow 42.5 \text{ d}$ 

Type IIIa Mapping: Low Magnification – Single Field Equivalent High Analytical Time due to slow SEM Stage Movement

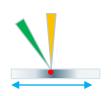
#### For SEM-EDS/WDS:

Not Practical or Realistic use of Analytical Equipment.

For SEM-XRF (Micro-XRF)

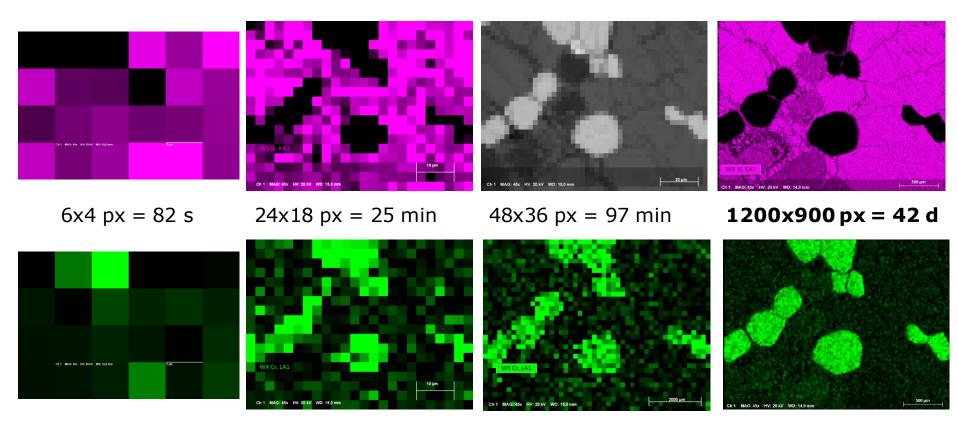
This is standard method, but slow. Fixed X-ray beam.

# Stage Mapping using SEM Stage Sample 2 at low magnification SEM-EDS/WDS



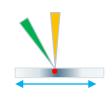


Effective time: 3.4 s / per pixel



Type IIIa Mapping: Low Magnification – Single Field Equivalent High Analytical Time due to slow SEM Stage Movement

# Stage Mapping using SEM Stage Sample 2 at low magnification SEM-XRF





#### Large Area Map

Sample Size: Polished Section: 45 x 30 mm

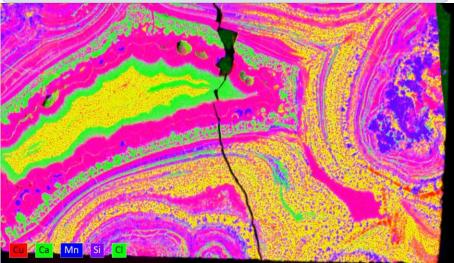
Sample from El Tesoro, Chile.

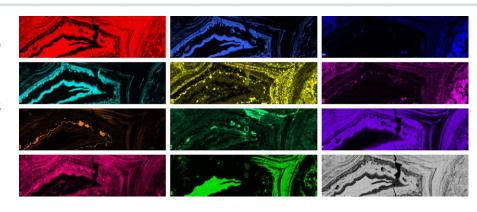
Clearly Defined Elemental and Mineralogical Phases Can identify the presence of trace elements, in this case, Cobalt (Co), Manganese (Mn), Strontium (Sr)

#### Analytical Parameters:

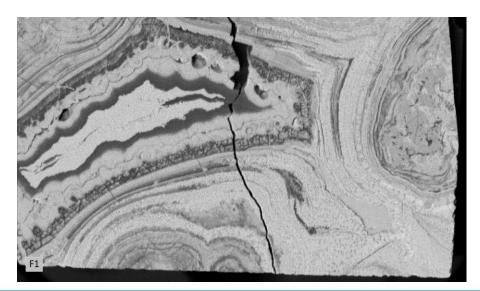
Tube Voltage: Rh at 50 kV Anode Current: 600 µA Pixel Spacing: 25 µm

Analytical Time: Rapid Stage 101 mins SEM Stage >800 mins



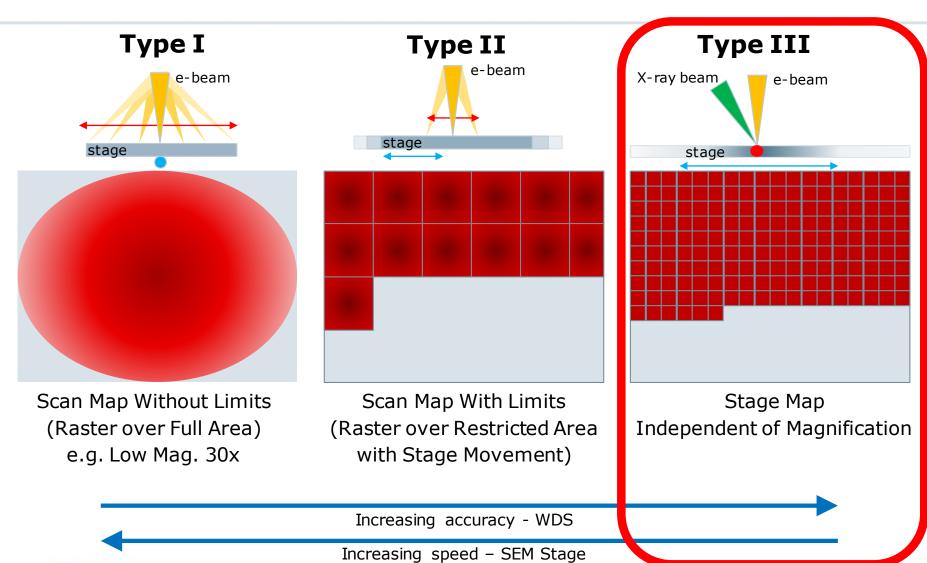


Top: Elemental Maps; Bottom Left: Mixed Elemental Map; Bottom, Right: X-Ray Intensity Map.

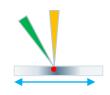


## Large Area Mapping Type IIIb: Rapid Stage

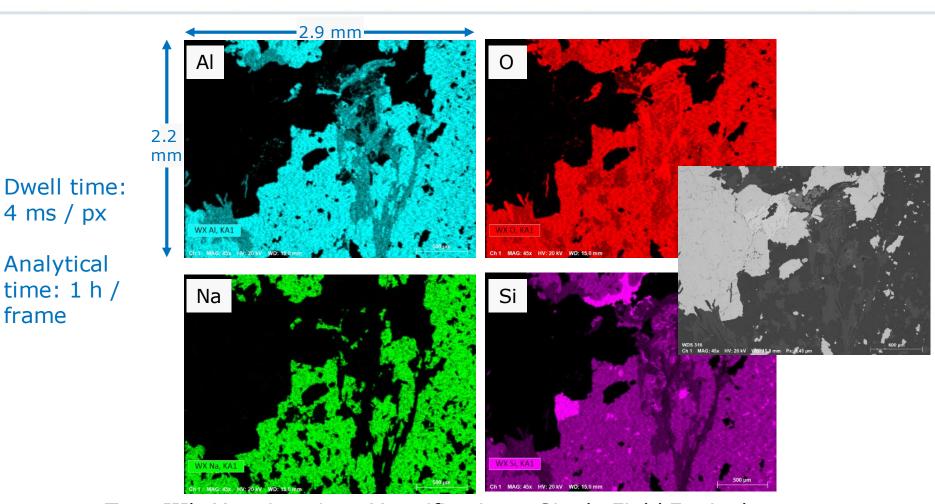




# Stage Mapping using Rapid Stage Sample 1 at low magnification

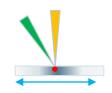






Type IIIb Mapping: Low Magnification – Single Field Equivalent High speed mapping with no artifacts

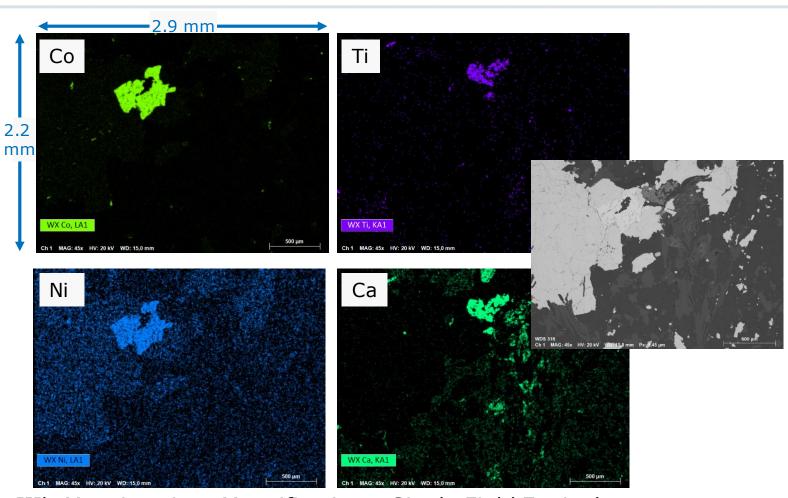
# Stage Mapping using Rapid Stage Sample 1 at low magnification







Analytical time: 1 h / frame



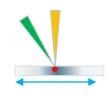
Type IIIb Mapping: Low Magnification – Single Field Equivalent High speed mapping with no artifacts

### Stage Mapping using Rapid Stage Sample 1 at low magnification

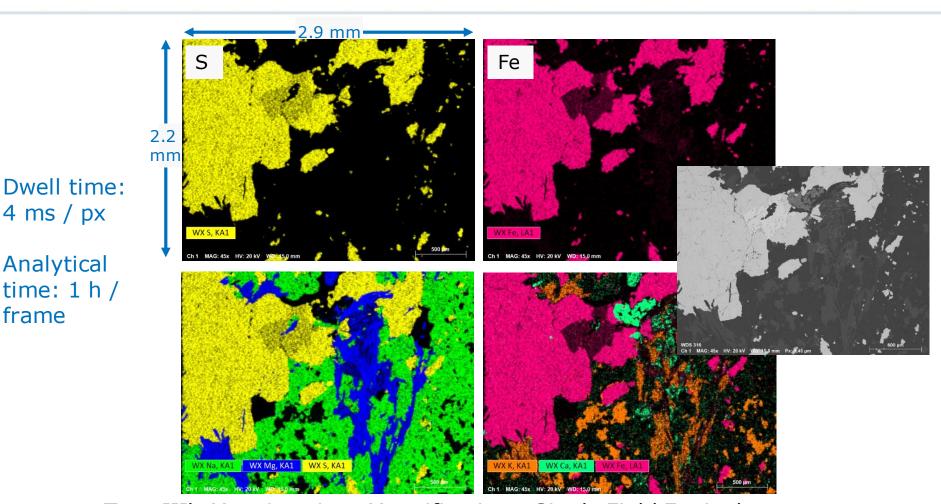
4 ms / px

Analytical time: 1 h /

frame

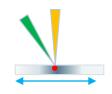




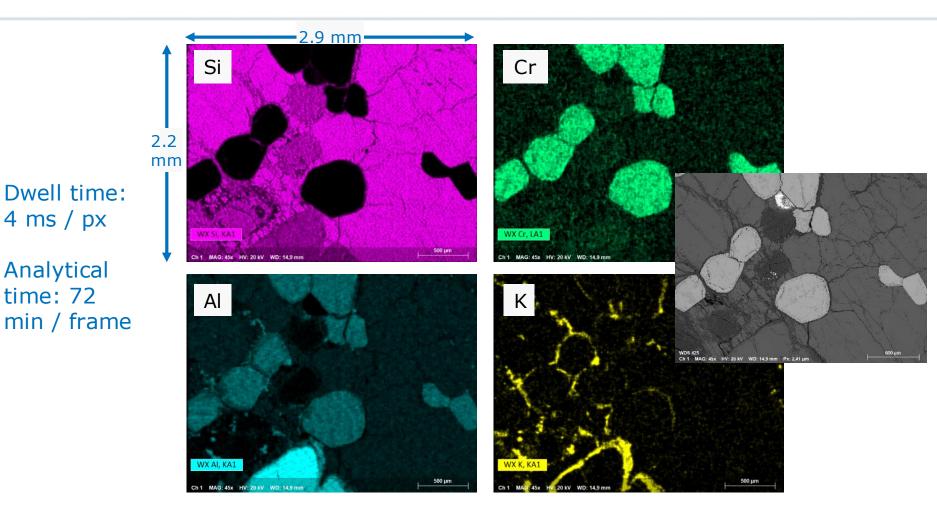


Type IIIb Mapping: Low Magnification - Single Field Equivalent High speed mapping with no artifacts

# Stage Mapping using Rapid Stage Sample 2 at low magnification

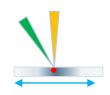






Type IIIb Mapping: Low Magnification – Single Field Equivalent High speed mapping with no artifacts

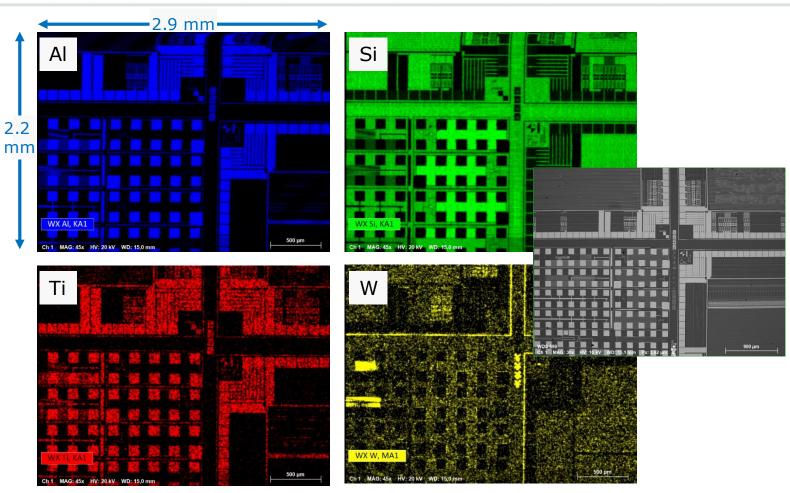
# Stage Mapping using Rapid Stage Sample 3 at low magnification





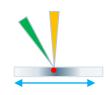


Analytical time: 2 h / frame

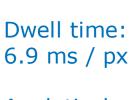


Type IIIb Mapping: Low Magnification – Single Field Equivalent High speed mapping with no artifacts

# Stage Mapping using Rapid Stage Sample 3 at low magnification





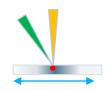


Analytical time: 2 h / frame

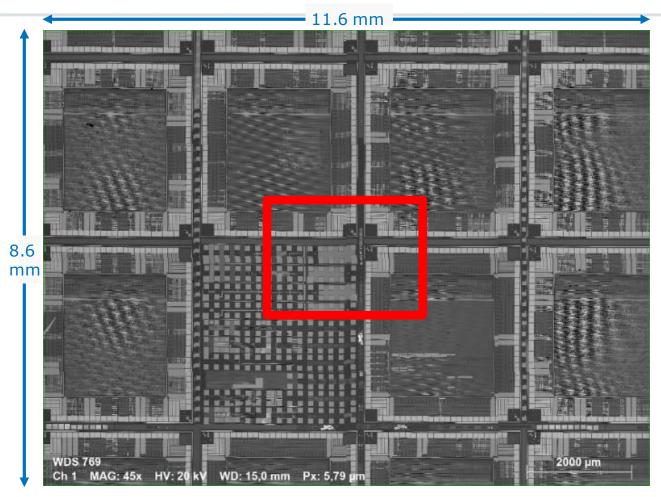


Type IIIb Mapping: Low Magnification – Single Field Equivalent High speed mapping with no artifacts

### Stage Mapping using Rapid Stage Sample 3 extended area: 4x4



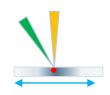




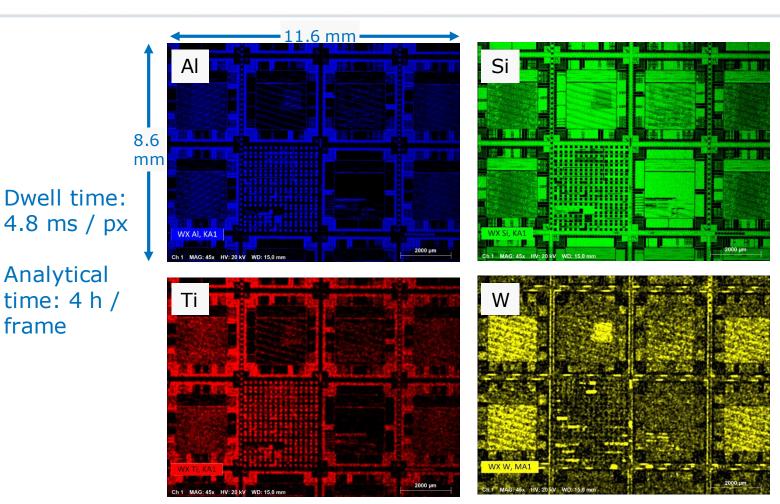
Type IIIb Mapping: Low Magnification – Multiple Field Equivalent High speed mapping with no artifacts

### Stage Mapping using Rapid Stage Sample 3 extended area

frame

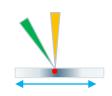




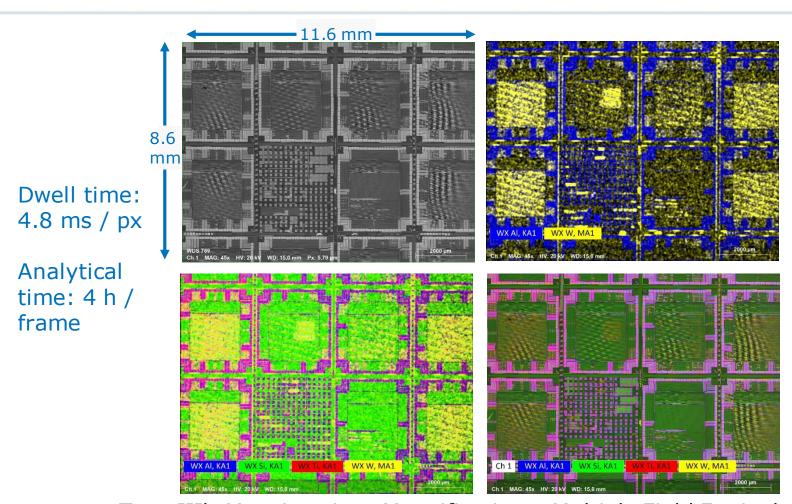


Type IIIb Mapping: Low Magnification – Multiple Field Equivalent High speed mapping with no artifacts

# Stage Mapping using Rapid Stage Sample 3 extended area

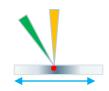




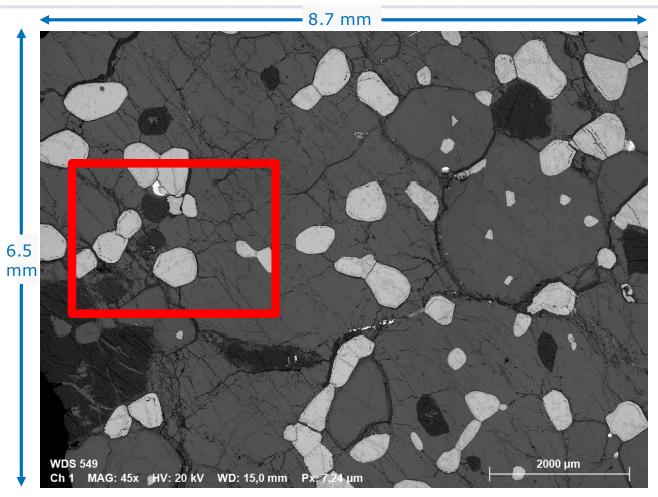


Type IIIb Mapping: Low Magnification – Multiple Field Equivalent High speed mapping with no artifacts

### Stage Mapping using Rapid Stage Sample 2 extended area: 3x3

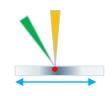




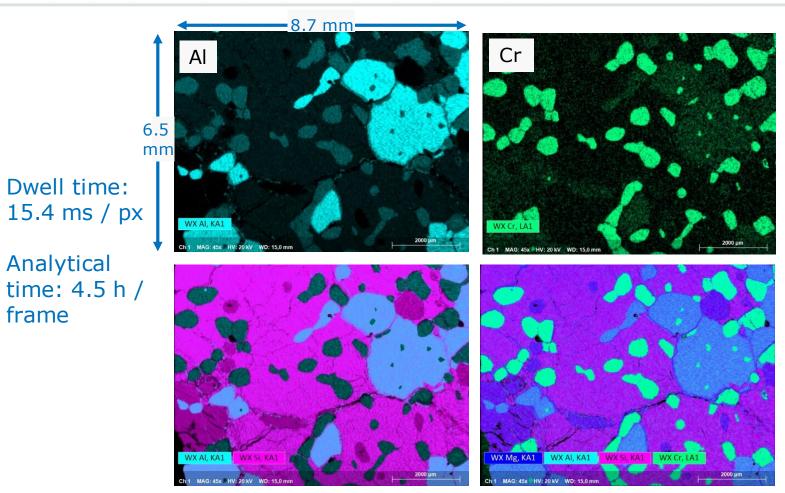


Type IIIb Mapping: Low Magnification – Multiple Field Equivalent High speed mapping with no artifacts

# Stage map using Rapid Stage Sample 2 extended area



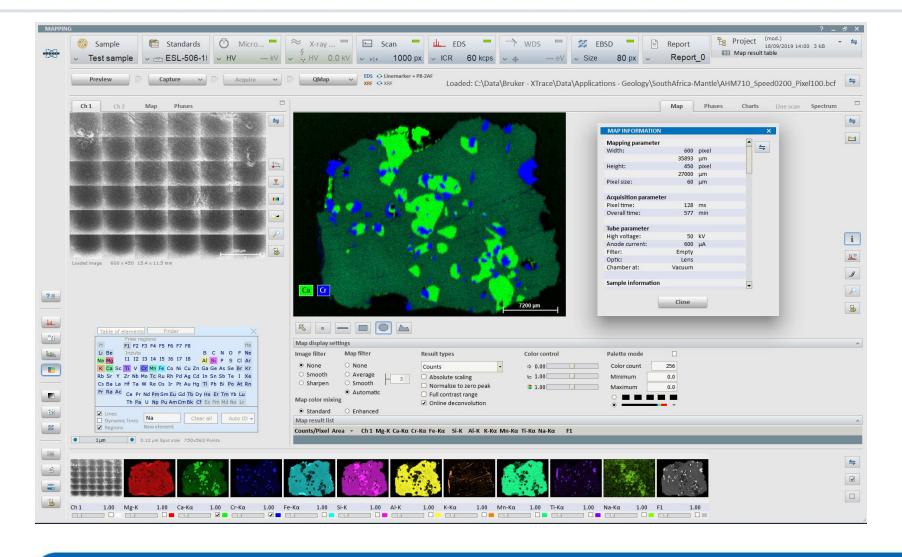




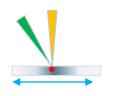
Type IIIb Mapping: Low Magnification – Multiple Field Equivalent High speed mapping with no artifacts

# Stage Mapping using Rapid Stage Sample 2 extended area

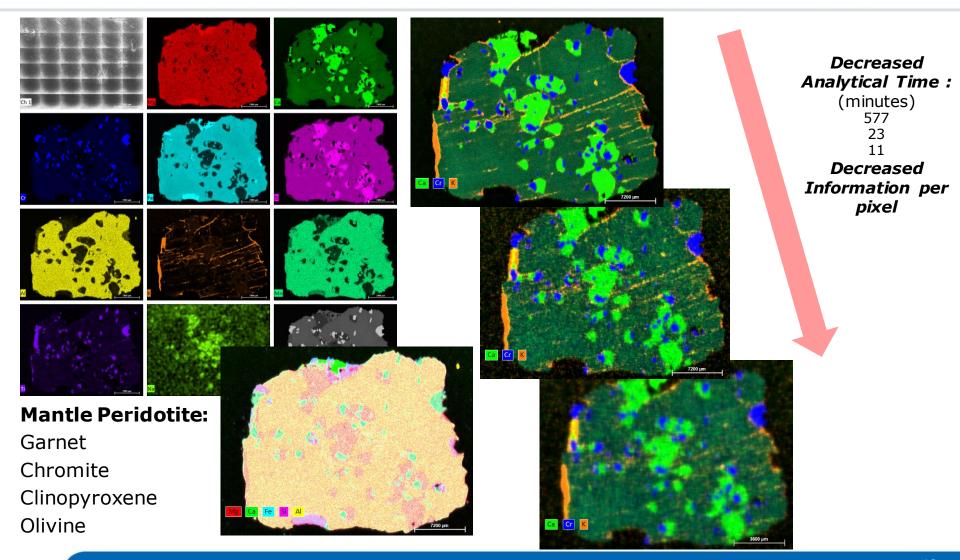




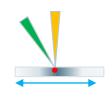
# Stage Mapping using Rapid Stage Sample 2 extended area



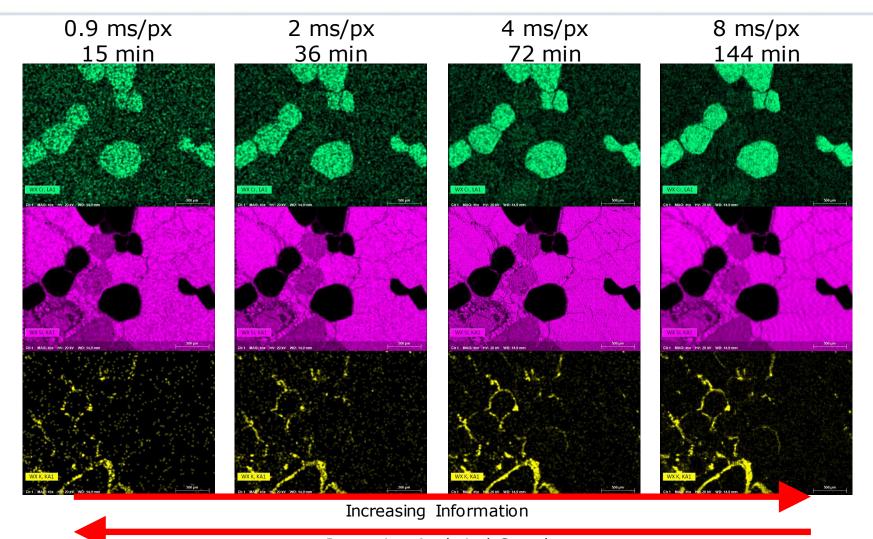




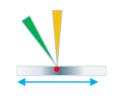
### Stage Mapping using Rapid Stage Effect of acquisition time



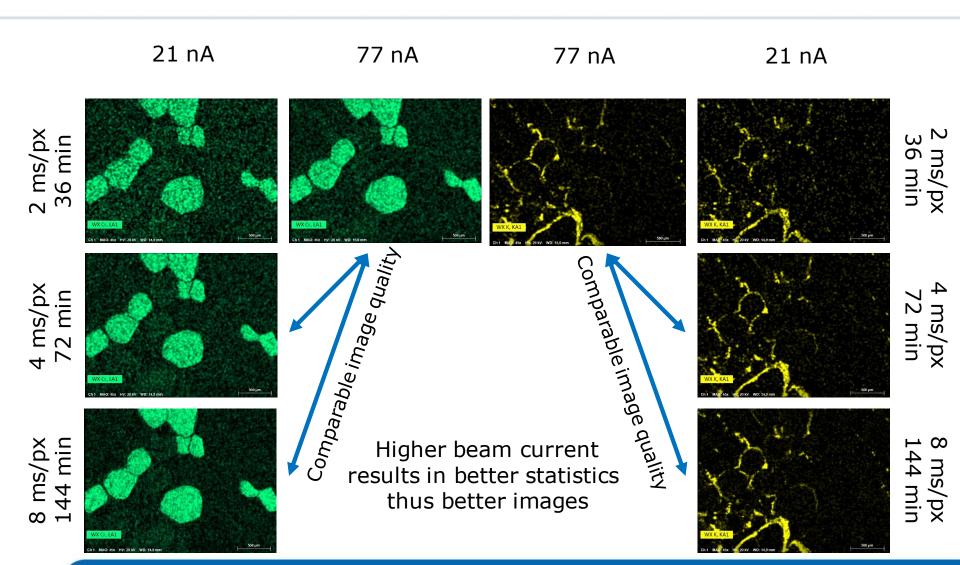




#### Stage Mapping using Rapid Stage Effect of beam current







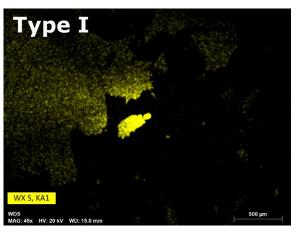
### Large Area Mapping Summary Mapping Types I, II, IIIa and IIIb



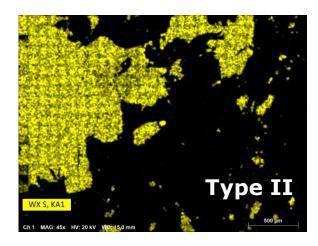
		FOV (mm)	FOV (px)	WDS Dwell time (ms/px)	Time /image (min)	Remarks
	Type I: Raster Map	2.9 x 2.2	1200 x 900	8	60	Lateral intensity loss
<b>←</b>	Type II: Raster Map with Tiles	2.9 x 2.2	1200 x 900	8	360	Tiling may be visible
	Type Illa: SEM Stage Map	2.9 x 2.2	1200 x 900	8	60,480	Extremely slow
	Type IIIb: Rapid Stage Map	2.9 x 2.2	1200 x 900	8	144	Fast and correct

### Comparing mapping types Sample 1 at low magnification

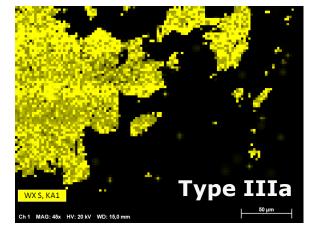




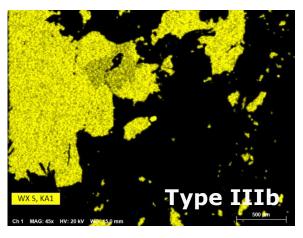
- ✓ Extremely fast
- Inaccurate at low magnificat ion



- Relatively fast
- Tiling may be visible



- ✓ Accurate
- ✓ Extremely slow



- √ Very fast
- Accurate

### Summary and Conclusions: Rapid Stage Benefits



#### **Fast mapping**

- Increase in speed by significant factor:
  - Especially for WDS and SEM-XRF use
- Enhancing WDS and SEM-XRF usability
- SEM Stage communication not designed for on-the-fly measurment

#### **Accurate results**

- Mapping with a vertical beam
- Avoiding violation of Bragg conditions
- Avoiding lateral intensity loss
- Supports simultaneous analysis with e-beam and X-ray beam or EDS and WDS.

#### Summary and Conclusions: Rapid Stage and Micro-XRF



- Can work in combination with SEM e-beam
  - Commonly Low-KV due to charging and sample interaction
- $\triangleright$  The analysis of samples in mircometers ( $\mu$ m) scale on a standard SEM.
- Able to perform large area maps on a variety of samples.
- Sample Preparation Minimal for Micro-XRF
  - No carbon-coating
  - No polishing
  - Directly into the SEM
- Able to detect and resolve minor and trace elements
- Identification of high energy X-Ray lines

#### Questions and Answers



#### **Are There Any Questions?**

Please type in the questions you might have in the Q&A box and press *Send*.

#### More Information



#### For more information, please contact us:

#### **Bruker Nano GmbH**

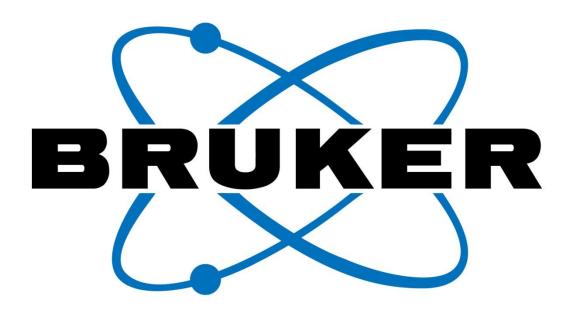
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