

Tribology 101 – 2: Characterizing the Tribo-system and Defining the Tribo-test



SJ Shaffer, Ph.D. – Bruker's Tribology and Mechanical Testing Business
steven.shaffer@bruker-nano.com



Elements of “The Tribosystem”



- **First Question: What is the intended application?**
 - Knowing the application helps us select the tribo-elements we need to incorporate in the tribo-test.
- **The Tribo-elements include:**
 - 1. Materials**
 - 2. Contact Geometry**
 - 3. Loading**
 - 4. Motion**
 - 5. Environment**

Let us examine each of these areas in more detail.

Let us try to list all the possible contributing factors which can define a tribo-system.

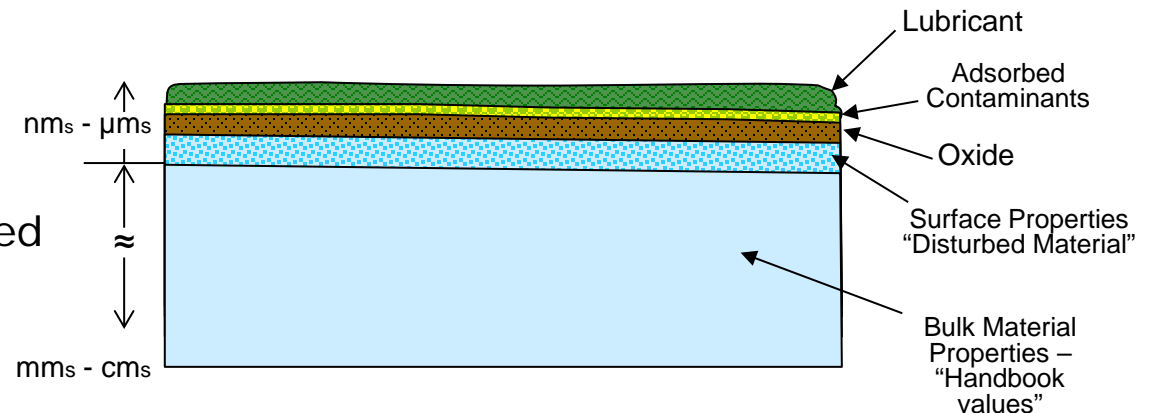
Elements of the Tribo-System

1. Materials – (a)



- **Solid bodies**

- Bulk Materials
 - Basic Composition
 - Heat Treatment
- Oxides
 - Thin, adherent
 - Thick, loosely bonded
- Coatings
 - Thin
 - Thick
- Lubricants
 - Anti-wear or EP Additives?
 - Viscosity, VI, or VP characteristics?
- Adsorbed Layers
- Contaminants

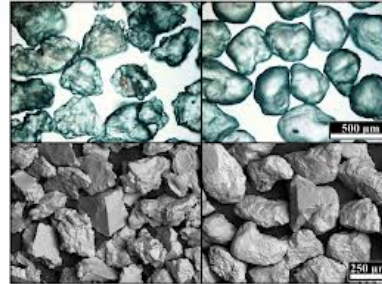


1. Materials – (b)



- **Loose Particles**

- Composition
- Hardness
- Size distribution
- Shape/Angularity
- Slurry?
 - Concentration
- Gas stream?
 - Concentration
 - Velocity
 - Angle of impact

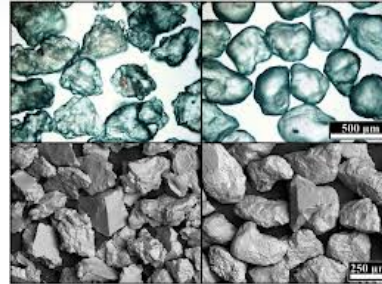


1. Materials – (b)



- **Loose Particles**

- Composition
- Hardness
- Size distribution
- Shape/Angularity
- **Slurry?**
 - Concentration
- Gas stream?
 - Concentration
 - Velocity
 - Angle of impact

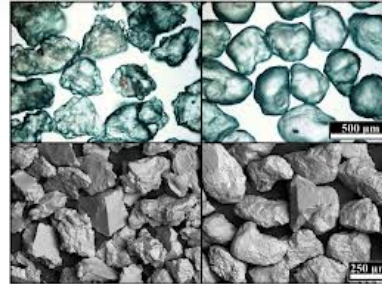


1. Materials – (b)

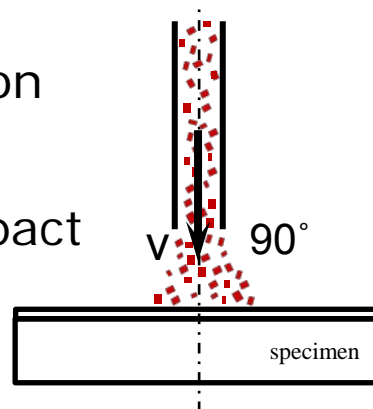


- **Loose Particles**

- Composition
- Hardness
- Size distribution
- Shape/Angularity
- Slurry?
 - Concentration



- **Gas stream?**
 - Concentration
 - Velocity
 - Angle of impact

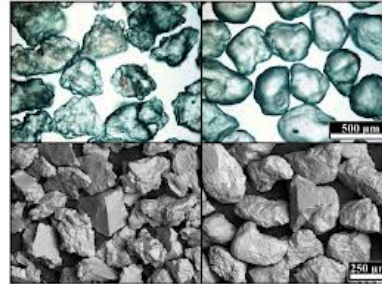


1. Materials – (b)

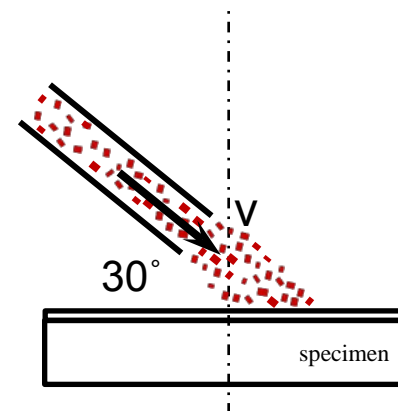
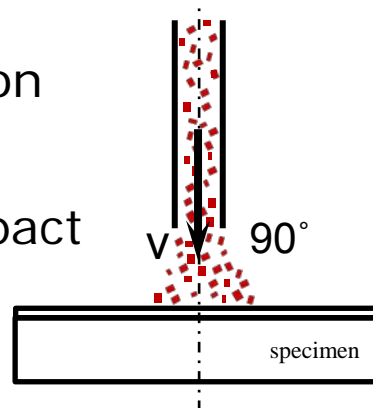


- **Loose Particles**

- Composition
- Hardness
- Size distribution
- Shape/Angularity
- Slurry?
 - Concentration



- **Gas stream?**
 - Concentration
 - Velocity
 - Angle of impact



2. Contact Geometry (a)



- **Macroscopic Geometry of Contact**
 - **Flat-on-Flat** (disk brake or gate valve)
 - Conformal
 - Non-Conformal
 - Point, line, ellipse
- **Surface Finish or Roughness**
 - R_a , R_q
 - Bearing Area
 - Peak shape
 - Valley volume
 - Lay (directionality of marks)
- **Edge conditions**
 - Sharp, as-machined edge or burr
 - Chamfer or radius



2. Contact Geometry (a)



- **Macroscopic Geometry of Contact**

- Flat-on-Flat
- **Conformal** (drum brake, plug valve or journal bearing)
- Non-Conformal
 - Point, line, ellipse

- **Surface Finish or Roughness**

- R_a , R_q
- Bearing Area
- Peak shape
- Valley volume
- Lay (directionality of marks)

- **Edge conditions**

- Sharp, as-machined edge or burr
- Chamfer or radius

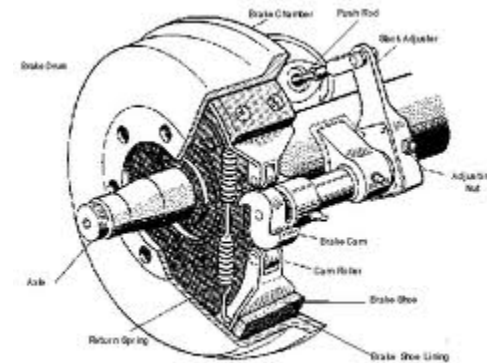


Figure 52 Scott Air Brake

2. Contact Geometry (a)



- **Macroscopic Geometry of Contact**

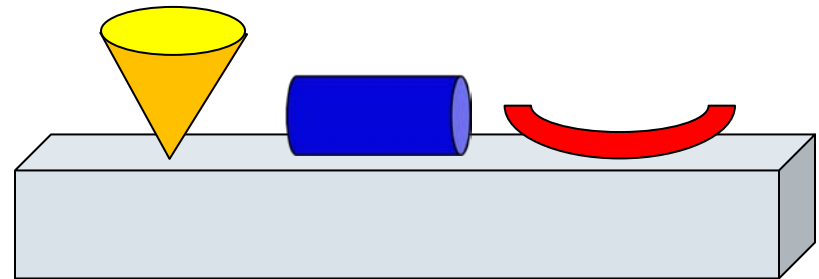
- Flat-on-Flat (disk brake)
- Conformal (drum brake)
- **Non-Conformal**
 - Point, line, ellipse

- **Surface Finish or Roughness**

- R_a , R_q
- Bearing Area
- Peak shape
- Valley volume
- Lay (directionality of marks)

- **Edge conditions**

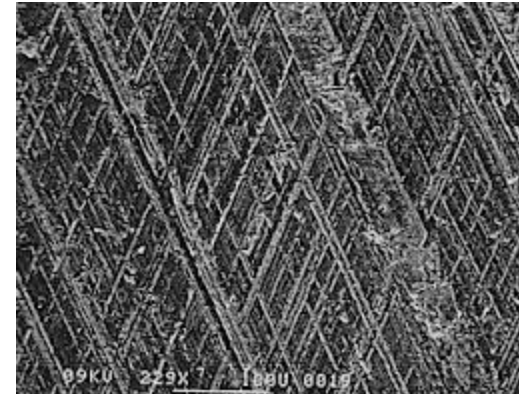
- Sharp, as-machined edge or burr
- Chamfer or radius



2. Contact Geometry (b)



- Macroscopic Geometry of Contact
 - Flat-on-Flat (disk brake)
 - Conformal (drum brake)
 - Non-Conformal
 - Point, line, ellipse
- **Surface Finish or Roughness**
 - R_a , R_q
 - Bearing Area
 - Peak shape
 - Valley volume
 - Lay (directionality of marks)
- Edge conditions
 - Sharp, as-machined edge or burr
 - Chamfer or radius



Cross-honed Cylinder

2. Contact Geometry (c)



- Macroscopic Geometry of Contact

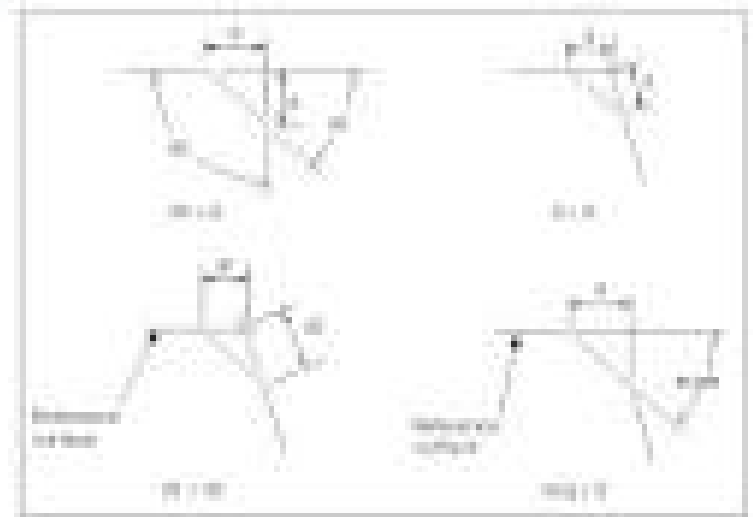
- Flat-on-Flat (disk brake)
- Conformal (drum brake)
- Non-Conformal
 - Point, line, ellipse

- Surface Finish or Roughness

- R_a , R_q
- Bearing Area
- Peak shape
- Valley volume
- Lay (directionality of marks)

- **Edge conditions**

- Sharp, as-machined or stamped edge or burr
- Chamfer or radius



Edge Machining Instructions

To the extent possible, the samples should be finished in the same manner as the real-life components.

3. Loading



- **Contact Stress**

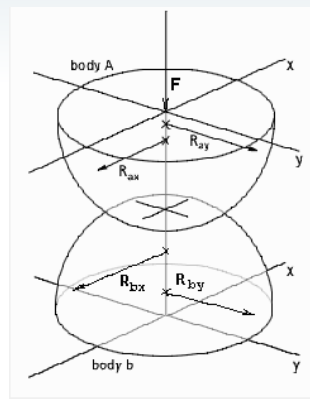
- **Elastic/Hertzian** (usually from rolling contact)
- **Plastic** (usually from sliding contact)

- **Steady, Increasing, Decreasing Load**

- **Variable Load**

- **Fixed Load Direction**

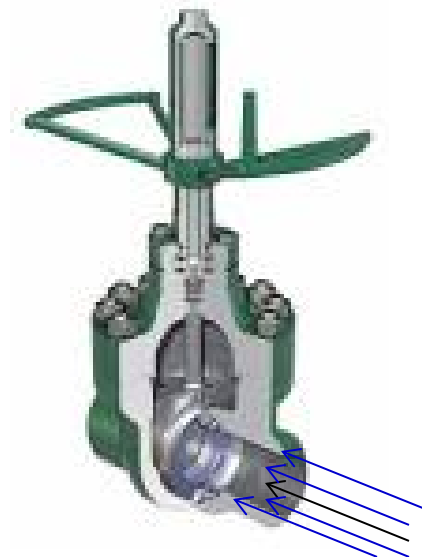
- **Oscillating Load**



3. Loading



- Contact Stress
 - Elastic/Hertzian (usually from rolling contact)
 - Plastic (usually from sliding contact)
- **Steady, Increasing or Decreasing Load**
- Variable Load
- Fixed Load Direction
- Oscillating Load

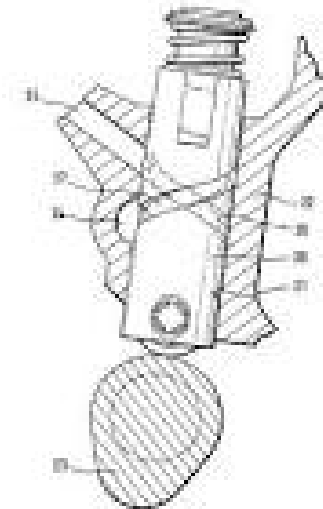


Gate Valve

3. Loading



- Contact Stress
 - Elastic/Hertzian (usually from rolling contact)
 - Plastic (usually from sliding contact)
- Steady, Increasing or Decreasing Load
- **Variable Load**
- Fixed Load Direction
- Oscillating Load

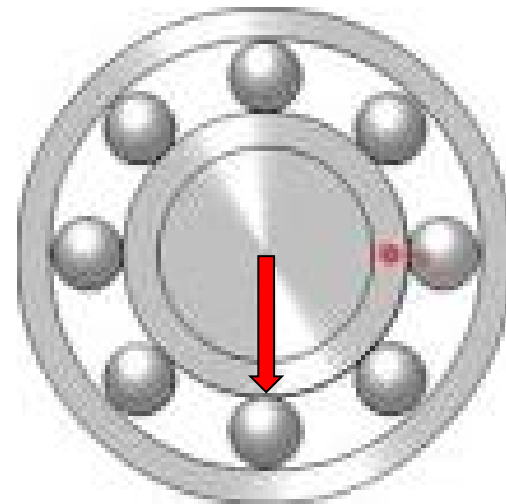


Cam Follower

3. Loading



- Contact Stress
 - Elastic/Hertzian (usually from rolling contact)
 - Plastic (usually from sliding contact)
- Steady, Increasing or Decreasing Load
- Variable Load
- **Fixed Load Direction**
- Oscillating Load



3. Loading



- Contact Stress
 - Elastic/Hertzian (usually from rolling contact)
 - Plastic (usually from sliding contact)
- Steady, Increasing or Decreasing Load
- Variable Load
- Fixed Load Direction
- **Oscillating Load**



Pendulum

4. Motion



- Continuous
- Stop/Start
 - Unidirectional
 - Reciprocating
- Duty Cycle
 - Dwell Time between sliding events

5. Environment



- Temperature
- Humidity
- Pressure
 - Ambient
 - Vacuum
 - High Pressure
- Liquid
- Electrolyte

Defining the Tribology-Test

Defining the Tribotest



- Always begin with: **What is the intended application?**
- Then determine: **What are the important parameters in specific areas of?**
 1. Materials
 2. Contact Geometry
 3. Loading
 4. Motion
 5. Environment

Defining the Tribotest



- Remember, **not everything is going to have an important or measurable effect.**
- So we can be pragmatic and thorough at the same time.

Defining the Tribotest: Material Example - "steel".



- Do we need the exact heat treatment?
 - If it is an **abrasive wear** situation, and our abradata's hardness is near that of the steel in its heat treated condition, then we had better use the same heat treatment on our samples.
 - If it is a situation in which we are running **fully hydrodynamic**, then the heat treatment doesn't really matter, but replicating the surface finish is important.

A Few Examples

Examples



- Wheel on Rail (rolling, sliding)
- Brakes/Clutches
- Journal Bearing - Hydrodynamic
- Sleeve Bearing – Boundary
- Abrasion-Resistant Material or Coating
- Low Friction Material or Coating
- Prosthetic Hip Joint
- Gate Valve in High Temp Steam System

Example: Wheel-on-Rail

Application 1a: Railroad



- **Critical Tribo-Elements:**

Materials

Alloy Steel: Composition, Heat Treatment, Hardness, Case Depth (if any)

Contact Geometry

Non-Conformal Line Contact, Disk Edge-on-Flat, 0.5 m radius, 75 mm contact width

Surface roughness, below a maximum value, is unimportant (becomes polished due to mild abrasion and plastic deformation of the asperities)

Loading

“25 Tons per axle”, Hertzian Contact, (111,000 N = 322 MPa)

Motion

Rolling Contact (possibly some side slip), primarily unidirectional. Speed based on 1 m diam wheel @ 200 kph

Environment

Dry, or wet with water or contaminants.
Oxides are probably unimportant.
Ambient outdoor temperature range.

Stress Calculation



Railroad Wheel on Rail

500 mm

200 GPa

0.3

111,000 N

75 mm

321.7 MPa

The screenshot shows the 'Hertzian Contact Calculator' window with the following data:

Parameter	Value	Unit
Body A Radius (Ra)	500	mm
Body A Elastic Modulus	200	GPa
Body A Poisson's Ratio	0.3	
Body B Radius (Rb)	0	mm
Body B Elastic Modulus	200	GPa
Body B Poisson's Ratio	0.3	
Normal Load (F)	111000	N
Unit Length (L)	75	mm
Max. Pressure	321.7	MPa
Max. Shear Stress	96.53	MPa
Depth of Max Shear	2342	μm
Contact Width	5.856	mm

The diagram on the right illustrates the contact geometry between two cylinders, 'body a' and 'body b', with radii R_a and R_b respectively. A normal force F is applied to the top cylinder, and the contact length is denoted as L .

Example: Wheel-on-Rail Application 1a: Railroad



- **Defining the Tribo-Test:** COF, rolling contact fatigue, slip

Materials

Alloy Steel: Same Composition, Heat Treatment, Hardness, Case Depth (if any)

Contact Geometry

Non-Conformal Line Contact, Roller-on-Roller

Loading

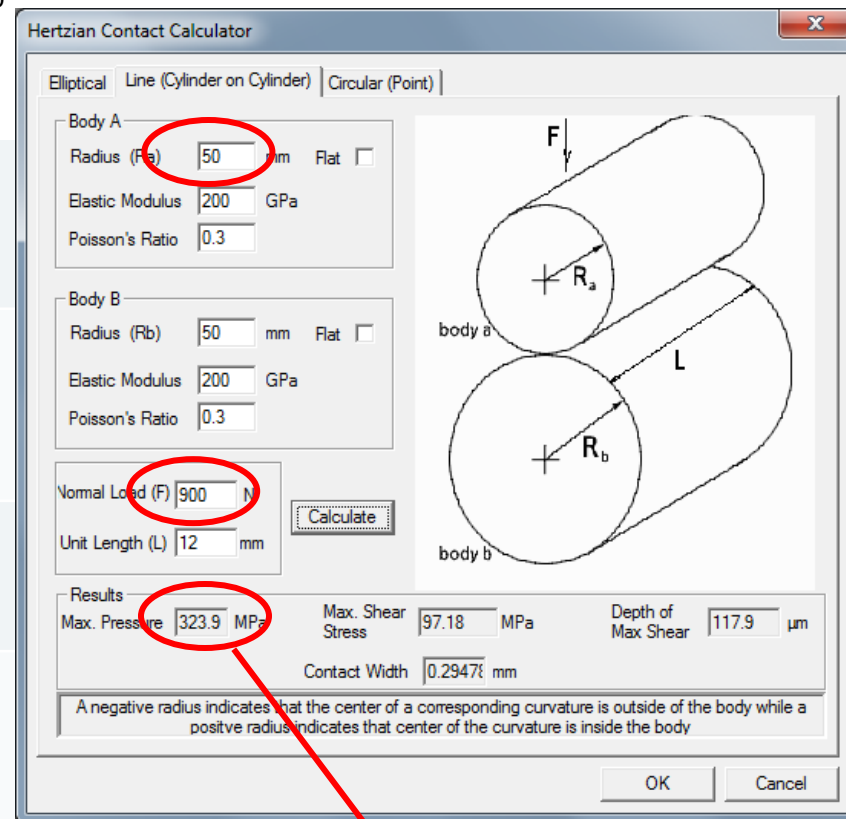
Hertzian Contact – 100 mm x 12 mm vs. 100 mm x 12 mm. = 324 MPa

Motion

Rolling Contact (can add slip)
Speed required = 10,600 rpm

Environment

Dry, or wet with water or contaminants. Ambient outdoor temperature range may not matter.



323.9 MPa

Lab Set-Up



Example: Wheel-on-Rail

Application 1b: Overhead



- **Critical Tribo-Elements:**

Materials

“Alloy Steel: Composition, Heat Treatment, Hardness, Case Depth (if any). Alternatively - a “Coating”

Contact Geometry

Flat sliding or “scrubbing”, estimate about 13 cm² area
Surface roughness , unimportant - becomes worn due to moderate abrasion or adhesion

Loading

Stress is Unknown.
Best estimate is based on contact area and estimated load of 10 kN to 45 kN (~7.5 - 35 MPa)

Motion

Sliding Contact, bidirectional.
Speed based on 300 mm radius wheel at 1 m/sec rolling

Environment

Dry, Oxides are probably unimportant.
Maybe “mill dust”? Ambient shop temperature range.

Example: Wheel-on-Rail



Application 1b: Overhead Crane - Wear of Flange

- **Defining the Tribo-Test:** Sliding wear (abrasive/adhesive)

Materials	Various heat treatments for steel. Various coatings – thick overlays, hardfacings	A schematic diagram showing the contact between a wheel and a rail. Two overlapping circles represent the wheel and the rail. A horizontal line represents the contact surface. Two yellow dots mark the contact points, and a black arrow indicates the direction of sliding contact between them.
Contact Geometry	Flat on flat sliding	
Loading	Run tests in range of estimated service stress of: 15-70 MPa	
Motion	Reciprocating Sliding Contact ~ 40 mm stroke Sliding distance based on service life estimate of 5 traverses per day of full rail length (200 m), for one year. Speed ~ 25 mm/sec	
Environment	Dry. Can add “mill dust” if important. Normal Ambient shop range ~ normal lab temperature.	

Example: Brake and Clutch Materials

Application 2: COF and Wear



- **Critical Tribo-Elements:**



Materials

Friction Material vs. Cast Iron (or steel)

Contact
Geometry

Flat-on-Flat, or conformal (for drum brake)

Loading

From 2 MPa to 5MPa for cars, up to 7-10 MPa for HDV

Motion

Pure sliding, primarily unidirectional.
Max Speed based on 15-20 cm diam rotor @ vehicle speed
100 kph.

Environment

Dry, or wet with water or contaminants. Thermal condition
important.

Example: Brake and Clutch Materials

Application 2: COF and Wear

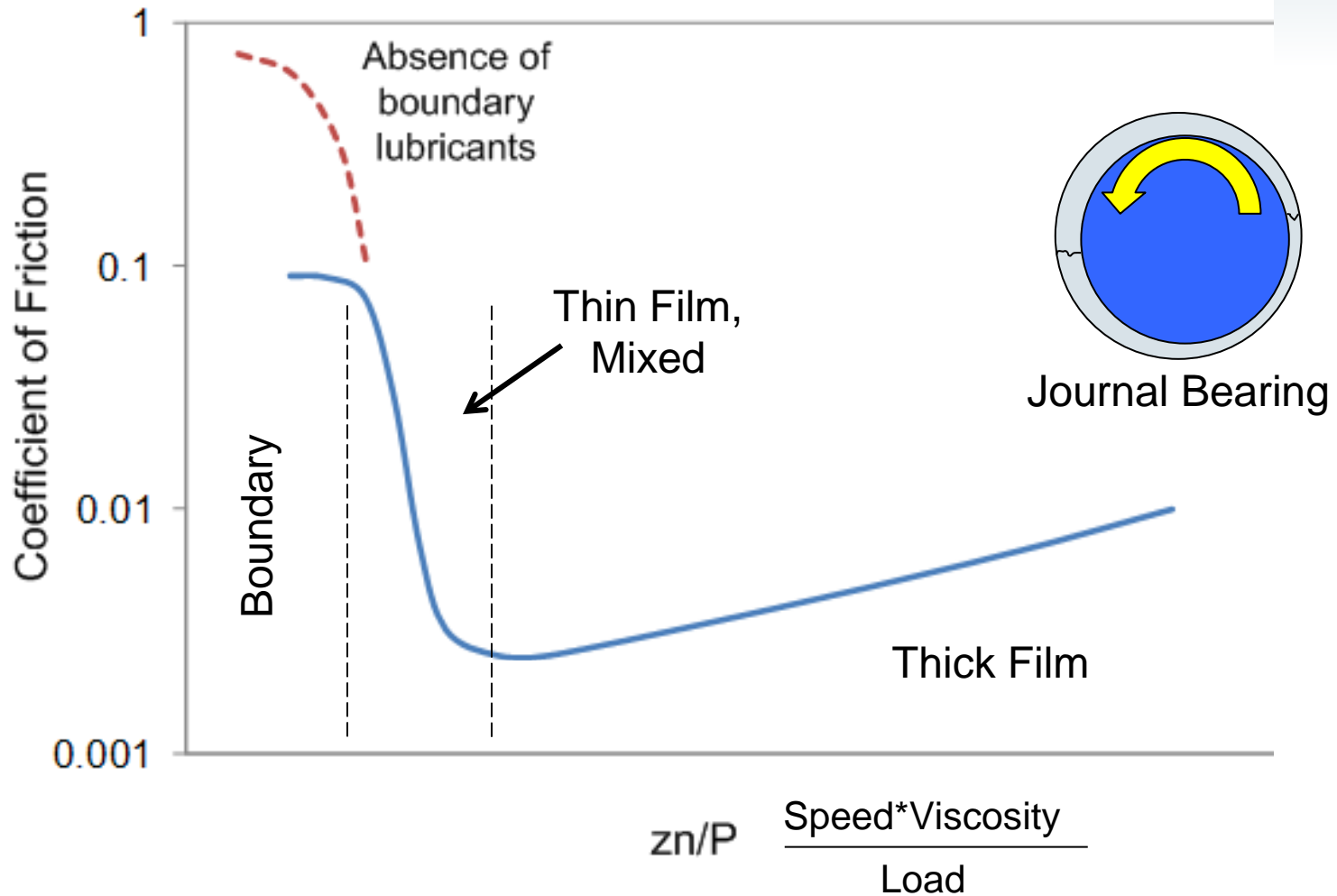


- **Define the Tribo-Test:** For material screening only – On-vehicle test required by regulators.

Materials	Friction Material vs. Cast Iron (or steel)
Contact Geometry	Flat-on-Flat, probably 3-button test (more stable), minimum button size ~ 1.5 cm diameter.
Loading	Select between 2 MPa and 5MPa, <u>constant load</u> or: Varying if running constant torque tests
Motion	Pure unidirectional sliding Multiple “stops” from max speed to zero.
Environment	Dry, for screening tests. Multiple stops with Initial Brake Temperature below 38 °C.

Short Tutorial on Stribeck Curve

Lubrication Regimes: The Stribeck Curve



Example: Hydrodynamic Bearing



Application 3: Lubricant Viscosity Characteristics

- **Characterize the Tribo-System:**

Materials Steel journal (shaft), Babbit or bronze bearing

Contact
Geometry Conformal, with converging gap.
Surface roughness ~ 0.1-0.2 μm R_a

Loading "1-2 hundred kg" on 2 main bearings, 50 mm x 20 mm
~ 2 MPa

Motion Unidirectional rotation of shaft.
Speed varies from "zero" rpm to ~ 6000 rpm.

Environ-
ment Liquid lubricant, possible temperature range
(automotive = -40 °C to 105 °C)

Example: Hydrodynamic Bearing



Application 3: Lubricant Viscosity Characteristics

- **Defining the Tribo-Test:** Stribeck Curve – Right hand Side

Materials	Steel journal, babbitt or bronze bearing (Steel likely OK, as long as surface roughness is replicated)
Contact Geometry	Converging gap. Can use cylinder-on-side versus flat disk. Surface roughness replicated 0.1-0.2 μm R_a
Loading	As needed to develop Stribeck Curve, depending on sample size and geometry, and relative speed of interface.
Motion	Unidirectional rotation of shaft. Speed varies from “low” rpm to “liftoff speed ~1000-2000 rpm.
Environment	Liquid lubricant of choice, controlled temperature range if needed for VI and VT work. (probably not to exceed -40 °C to 105 °C)

Example: Journal Bearing



Application 4: Boundary Lubricant Characteristics

- **Characterize the Tribo-System:**

Materials	Steel journal (shaft), Bronze bearing
Contact Geometry	Conformal, with converging gap. Surface roughness $\sim 0.2\text{-}0.4 \mu\text{m } R_a$
Loading	Up to 800 MPa, depending on application
Motion	1) Unidirectional rotation of shaft. 2) Reversing $\pm 25^\circ$ Speed varies from "zero" rpm to ~ 1000 rpm.
Environment	Grease lubricant, possible temperature range (Aerospace = -50°C to 170°C)

Example: Journal Bearing



Application 4: Boundary Lubricant Characteristics

- **Define the Tribo-Test:** Stribeck Curve – Left Hand Side COF, or PV Characteristics, or Wear Rate

Materials Steel journal (shaft) vs Bronze bushing, or Steel Pin vs Bronze Disc (or vice versa)

Contact Geometry Conformal journal bearing.
Or cylinder-on-disc or conformal block-on-ring
Surface roughness $\sim 0.2\text{-}0.4 \mu\text{m } R_a$

Loading Up to 150 MPa, step-wise for PV evaluation, or steady for wear

Motion 1) Unidirectional rotation of shaft for PV and COF.
2) Reversing $\pm 25^\circ$ for wear and “static” or breakaway COF
Speed can vary from 0.01 to 2-3 m/s, to simulate application

Environment Grease lubricant, possible temperature influence
(e.g. Aerospace = -50°C to 170°C)

Example: Abrasion-Resistant Coating

Application 5: Anti-Scratch coating for glass



- Characterize the Tribo-System:**



Materials	DLC, < 10 μm thick on SiO_2 vs. "dust" or other hard particles or objects
Contact Geometry	"Sharp" radius or angular point versus Flat; Elastic/Hertzian contact Surface roughness $\sim 0.05\text{-}0.1 \mu\text{m} R_a$
Loading	Unknown contact stress, could be as high as 15 GPa
Motion	Linear sliding contact, short sliding distance, likely unidirectional
Environment	Ambient

Example: Abrasion-Resistant Coating

Application 5: Anti-Scratch coating for glass



- **Define the Tribo-Test: Scratch Test**

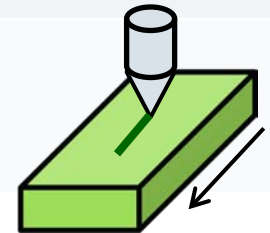
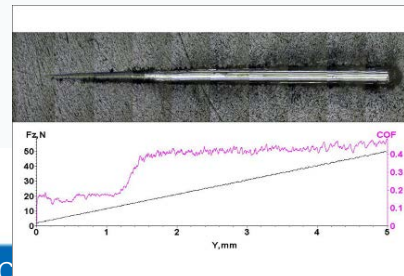
Materials DLC, < 10 μm thick on SiO_2 vs. diamond indenter

Contact Geometry Sharp, hard tip (e.g. 2.5, 12.5, 200 μm radius tip), depending on coating thickness
Surface roughness \sim 0.05-0.1 μm R_a , per application

Loading Linearly Increasing load until coating failure

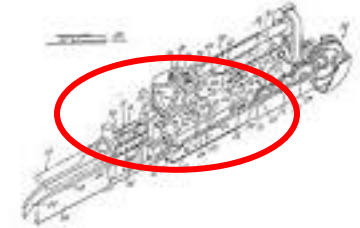
Motion Linear sliding contact, short sliding distance, Unidirectional, unless sample size and load gradient dictate alternate method, e.g. zig-zag scratch

Environment Ambient



Example: Low Friction Coating

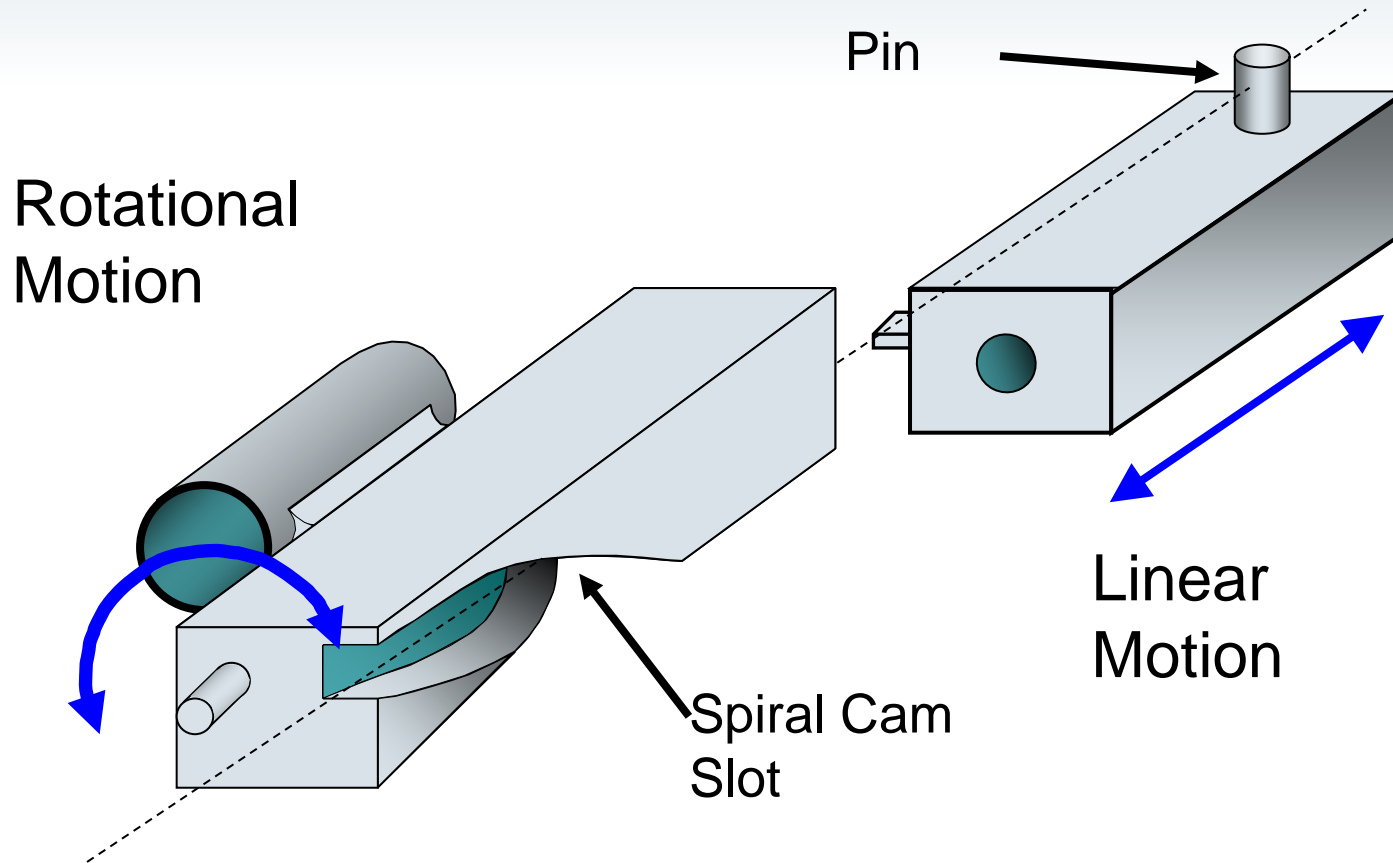
Application 6: Action Components for Lubricant-Free Machine Gun



- **Characterize the Tribo-System:**

Materials	Coating, up to 30 μm thick, or Surface Treatment, on High Strength Steel (AISI 4340), Self-mated
Contact Geometry	Cylinder-on-flat, cylinder on flat edge, flat-on-flat Surface roughness $\sim 0.4\text{-}0.8 \mu\text{m} R_a$
Loading	Up to 100 MPa (Hertzian calculated)
Motion	Linear reciprocating sliding, 40 mm sliding distance, total sliding distance 6,500 m, speed up to 350 cm/sec
Environment	Ambient, up to 150 $^{\circ}\text{C}$, No lubrication

Key Critical Interface: Pin-in-Spiral Cam Slot



Example: Low Friction Coating

Application 7: Action Components for Lubricant-Free Machine Gun



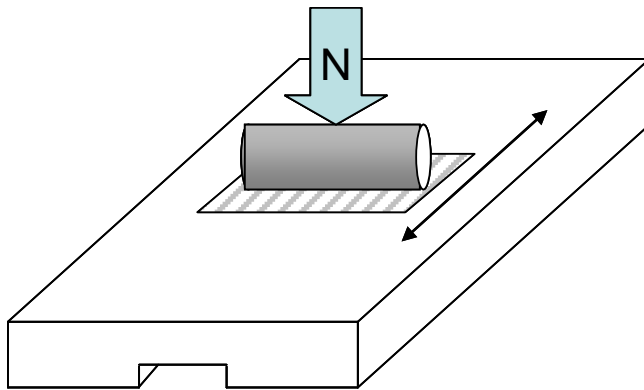
- **Define the Tribo-Test:** Sliding wear and COF

Materials	Various Coatings, on High Strength Steel (AISI 4340), Self-mated
Contact Geometry	Cylinder-on-flat, cylinder on flat edge, flat-on-flat (3-button) Surface roughness $\sim 0.4\text{-}0.8 \mu\text{m } R_a$, per application
Loading	Multiple lower loads for screening, up to 100 MPa stress
Motion	Linear reciprocating sliding, 40 mm stroke length Unidirectional to achieve tot. sliding distance $> 6,500 \text{ m}$, Speed up to 350 cm/sec
Environment	Ambient for screening, 150 °C for final testing

Tribology Experiments: Basic Rig & Sample Design

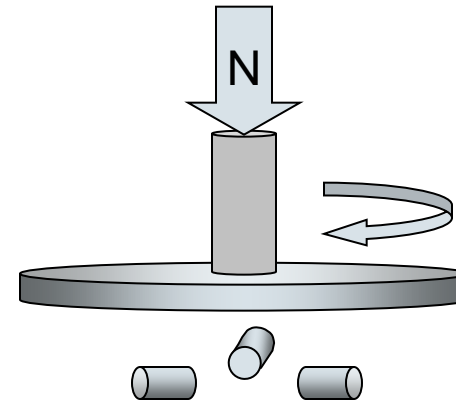


Reciprocating Tests



Pin-on-Side

Unidirectional Tests



3-Button

Example: Prosthetic Hip

Application 7 – Wear Rate and COF



- **Characterize the Tribo-System:**

Materials Al_2O_3 , Zr_2O_3 or CoCrMo vs. UHMWPE

Contact
Geometry Conformal – Ball-in-hemisphere
Surface roughness $\sim 0.2\text{-}0.4 \mu\text{m } R_a$

Loading Variable, including unloading

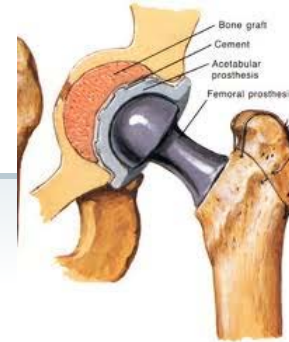
Motion Non-Linear, reciprocating sliding with cross
sliding/rotating.
Stroke length approximately 1-3 cm.

Environment 37 °C, Synovial Fluid lubrication



Example: Prosthetic Hip

Application 7 – Wear Rate and COF



- **Define the Tribo-Test:**

Materials

Al_2O_3 , Zr_2O_3 or CoCrMo vs. UHMWPE

Contact Geometry

Conformal or Non-Conformal for screening
Surface roughness $\sim 0.2-0.4 \mu m R_a$

Loading

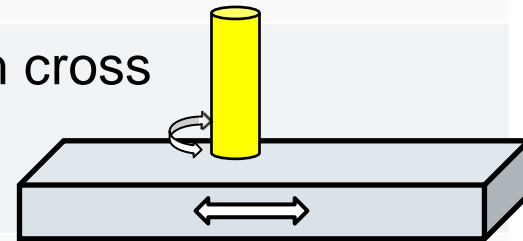
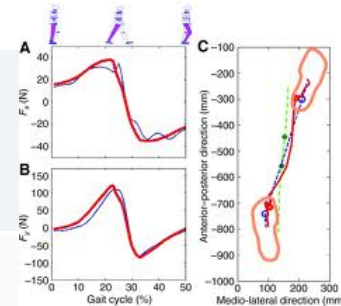
Variable, including unloading

Motion

Non-Linear, reciprocating sliding with cross sliding/rotating.
Stroke length approximately 1-3 cm.

Environment

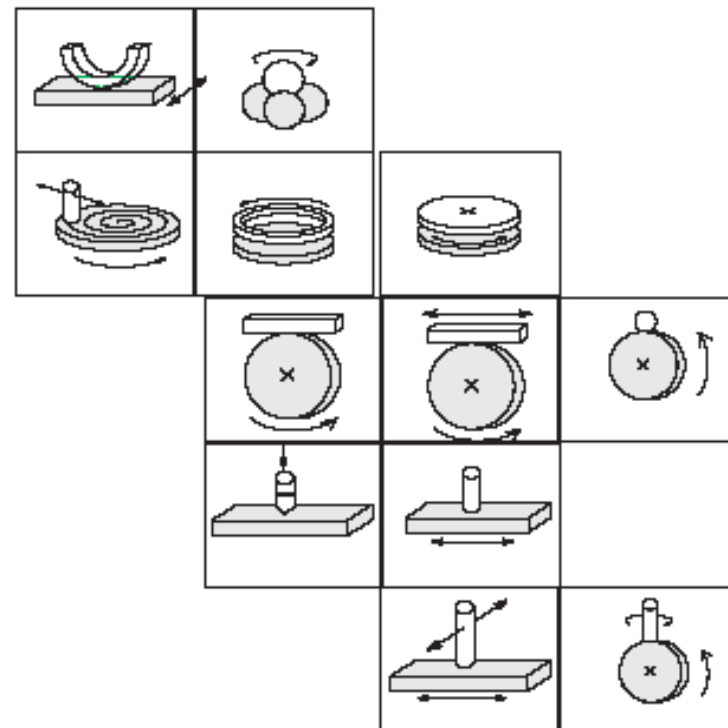
For Screening, 37 °C Saline Solution or Bovine Serum



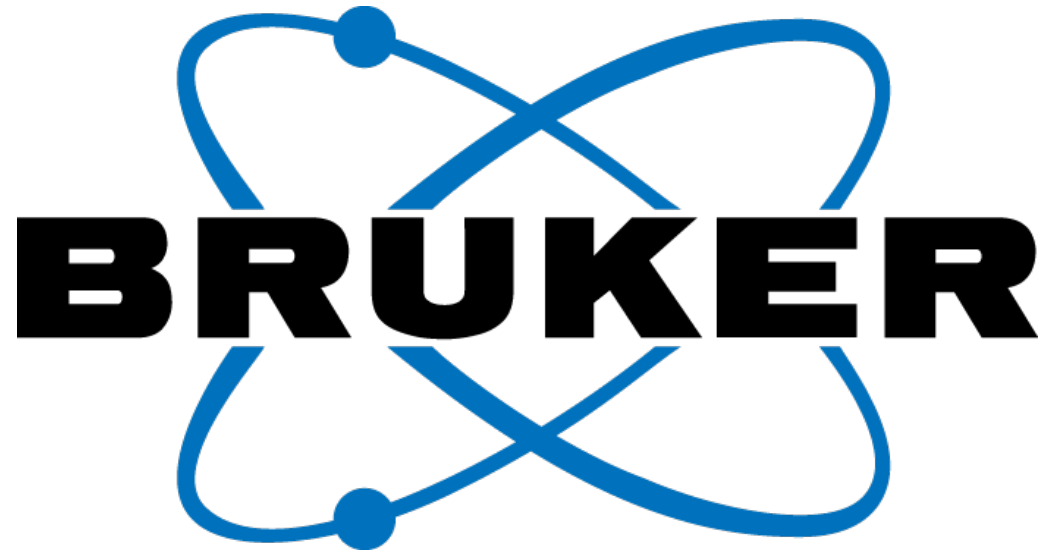
Tribology & Mechanical Testing (TMT)



- Universal platform for Tribology studies: Wear, Friction,.. when 2 surfaces meet.



- Large load range
- Wide variety of environments (corrosion, HT, liquid)
- Wide variety of configurations (rotating & translating motions)



www.bruker.com

steven.shaffer@bruker-nano.com